

on asynchrony and choreographies

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outline

1 *choreographies at a glance*

2 *asynchrony*

3 *conclusions*

overview of choreographies

choreographies

a model for distributed computation based on “common practice”

- used for modeling interactions between web services
- high-level languages, alice-and-bob notation
- good properties: message pairing, deadlock-freedom
- no orchestrator
- projectable to local views

different usages

- choreographies as specifications (types)
- choreographies as programs (executable)

the world of choreographies

common features (present in most languages)

- message passing/method selection
- conditional and (tail) recursion

additional features (only in particular languages)

- channel passing
- process spawning
- asynchrony
- web services
- ...

↪ the target language for projection reflects these design choices

our motivation

goal

- study foundational aspects of choreographies
- identify minimal primitives required for particular constructions
- framework: choreographic programming (but...)

↪ “bottom-up” approach, rather than “top-down”

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this work

asynchronous semantics

- uniform approach, applicable to different models
- reuse out-of-order execution

↪ hopefully cleaner than previous proposals

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$p \rightarrow q$

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a simple choreography model

syntax

$C ::= \mathbf{0} \mid p.e \rightarrow q; C$

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$$C ::= \mathbf{0} \mid p.e \rightarrow q; C$$

semantics

$$\frac{e \downarrow_p v}{p.e \rightarrow q; C, \sigma \rightarrow_s C, \sigma[q \mapsto v]} \text{Synch}$$

$$\frac{\{p, q\} \# \{r, s\}}{p.e \rightarrow q; r.e' \rightarrow s \equiv r.e' \rightarrow s; p.e \rightarrow q} \text{Swap}$$

$$\frac{C \equiv C_0 \quad C_0, \sigma \rightarrow_s C'_0, \sigma' \quad C'_0 \equiv C'}{C, \sigma \rightarrow_s C', \sigma'} \text{Struct}$$

↗ plus: \equiv is a congruence

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 - then $C \rightarrow_a \eta_1; \dots; \eta_n; t(q, v); C'$

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 - \rightarrow_s is a big-step semantics refined by \rightarrow_a

a possibility for \rightarrow_a

capitalize on swap

$$\frac{}{p.e \rightarrow q \equiv p.e \xrightarrow{x} \bullet_q; \bullet_p \xrightarrow{x} q} \text{Unfold}$$

$$\frac{e \downarrow_p v}{p.e \xrightarrow{x} \bullet_q; C, \sigma \rightarrow_a C[v/x], \sigma} \text{Async|Send}$$

$$\frac{}{\bullet_p \xrightarrow{v} q; C, \sigma \rightarrow_a C, \sigma[q \mapsto v]} \text{Async|Recv}$$

$$\frac{\{p\} \# \{r, s\}}{p.e \xrightarrow{x} \bullet_q; r.e' \rightarrow s \equiv r.e' \rightarrow s; p.e \xrightarrow{x} \bullet_q} \text{Swap'}$$

an example

$C = p.1 \rightarrow q; p.2 \rightarrow q; p.3 \rightarrow r$

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↪ the two “receive” actions at q cannot be swapped

results

desired properties

this relation satisfies the properties we identified earlier (see paper)

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furthermore

- formal correspondence with synchronous semantics
- projection theorem wrt an asynchronous process calculus

modularity

- adaptable to other communication primitives
 - label selection
 - name mobility

modularity

- adaptable to other communication primitives
 - label selection
 - name mobility
- nice interplay with other choreography primitives
 - minimal choreographies (see paper)
 - procedural choreographies (see our forte'17 paper + tr)
 - multiparty session types
 - ...

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conclusions

- asynchronous semantics for choreographic communication
- abstract(-ish) description of asynchrony (paper only)
- precise characterization in terms of synchronous communication
- modular development, easily adaptable/extendable

thank you!