

Left shifting machine:

$$q_0 \# w_1 w_2 \dots w_n \rightarrow q_{acc} w_1 w_2 \dots w_n$$

1. Move right and read character x

2. If $x = 'U'$

Move left

Write 'U'

stop

3. If $x \neq 'U'$

Move left

Write x

move right
goto 1.

TM which copies a string

$$q_0 w_1 w_2 \dots w_n \rightarrow q_{acc} w_1 w_2 \dots w_n w_1 w_2 \dots w_n$$

$$\underline{w}_1 w_2 \dots w_n \rightsquigarrow \underline{w}_1 w_2 \dots w_n \#$$

$$\rightsquigarrow w_1 \underline{w}_2 \dots w_n \# w_1$$

$$\rightsquigarrow \underline{w}_1 w_2 \dots w_n \# w_1 \dots w_n$$

$$\rightsquigarrow w_1 w_2 \dots w_n \# \underline{w}_1 \dots w_n$$

↓ leftshift

$$q_{acc} w_1 \dots w_n w_1 \dots w_n$$

No of operations: $O(|w|^2)$

Ex 3.11 (short version)

$$C = \{ a^i b^j c^k \mid i \cdot j = k, i, j, k \geq 1 \}$$

~~aaa~~ bbbcccc

check for yourselves!

Next step: other variants of TM's

Model 1: several tapes

k Tape TM: $\frac{\Delta w_1 w_2 \dots w_n}{\Delta}$
 $\frac{\Delta}{\Delta}$
 $\frac{\Delta}{\Delta}$
 $\frac{\Delta}{\Delta}$
 tape k $\frac{\Delta}{\Delta}$

NB: #tapes is fixed (k for a k-tape TM)
 $\delta(q, a_1 a_2 \dots a_k) = (p, b_1, \dots, b_k, \gamma_1, \gamma_2, \dots, \gamma_k)$

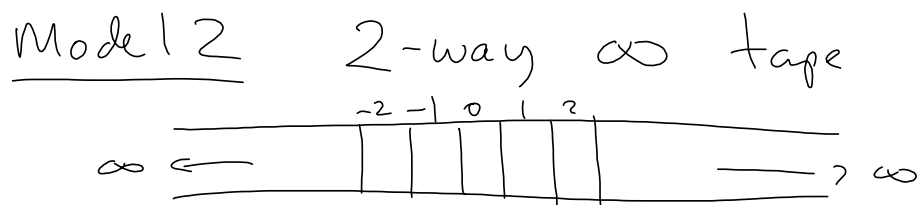
Why could several tapes be useful

ex copy:

$$\begin{array}{ccc} \underline{\Delta} w_1 w_2 \dots w_n & & \Delta w_1 w_2 \dots w_n \underline{\Delta} \\ \underline{\Delta} & \rightsquigarrow & \underline{\Delta} w_1 w_2 \dots w_n \end{array}$$

$$\rightsquigarrow \begin{array}{ccc} \Delta w_1 \dots w_n \underline{\Delta} w_1 \dots w_n & & \underline{\Delta} w_1 \dots w_n \underline{\Delta} w_1 \dots w_n \\ \Delta w_1 \dots w_n & \rightsquigarrow & \underline{\Delta} \end{array}$$

$O(|w|)$ steps



Model 3 Non-deterministic TM (NDTM)

loosely: a NDTM can guess

from state q on an a we may have

up to $B = |Q| \cdot |\Gamma| \cdot 3$

$\leftarrow (R, L, S)$

ex when non-determinism is useful:

Given $n \in \mathbb{Z}^+$

is n composite ($\exists? n_1, n_2 \geq 2$ s.t. $n_1 \cdot n_2 = n$)

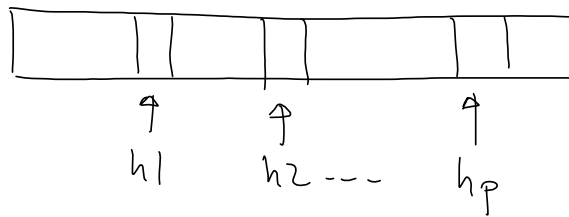
The NDTM guesses n_1 and n_2

calculates $m = n_1 \cdot n_2$ and

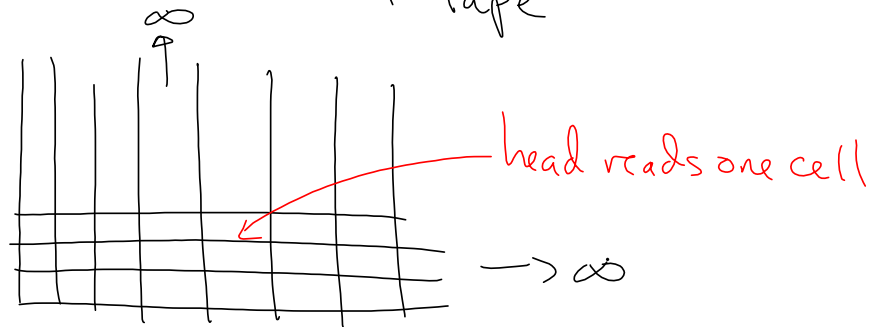
checks whether $m = n$.

Model 4 One tape and several heads

p-head TM

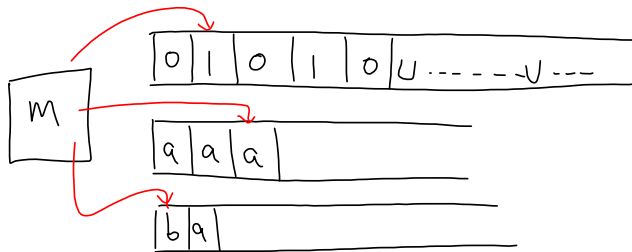


Model 5 2 dimensional tape



We want to argue that none of these models are stronger than standard TM model, ^{in particular} so if $L = L(M)$ for M being e.g. a k -tape TM then \exists stand TM M' s.t. $L = L(M')$

Simulating a 3-tape TM with a standard TM



M'

#	0	1	0	1	0	#	a	a	a	#	b	a
---	---	---	---	---	---	---	---	---	---	---	---	---

read overall description in Sipser.
We concentrate on how to implement one step of M .

Note that if M moves into 'u' area on any tape, M' can simulate this using shift right (several or on time)

k-tapes for original state q^i of M

We have states $q^i_{\uparrow(\alpha_1, \dots, \alpha_k)} \quad \alpha_i \in \{\Gamma, \cup\} - \}$

and states $p^i(\dots, b_1, b_2, \dots, b_k, \gamma_1, \dots, \gamma_k)$

If we are in state $q^i_{\uparrow(\beta_1, \dots, \beta_r)}$ then

We have collected the symbols being read on the first r tapes.

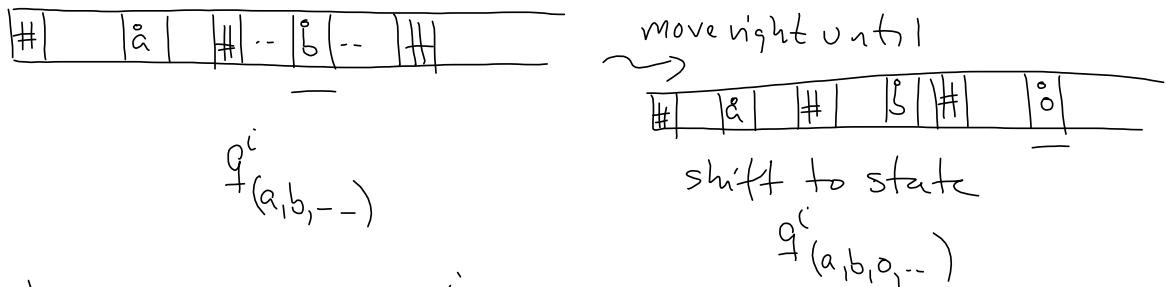
Note the # states above is huge, BUT
at most some function $f(k, |\Gamma|)$

How to implement one step of M
(step 2 page 177)

$$\text{in } M \quad \delta(q_i, a_1 \dots a_n) = (q_j, b_1 \dots b_k, \gamma_1 \dots \gamma_h)$$

1. M' starts in state $q^i(-, -, -)$

2. In state $q^i(\beta_1 \dots \beta_r, -, -)$ move head forward to copy of $r+1$ 'st tape that is



When we reach $q^i(\beta_1 \dots \beta_h)$ we all head characters

move to state $p^j(-, -, b_1, b_2, \dots, b_k, \gamma_1, \gamma_2, \dots, \gamma_h)$

In state q^j
 $(b_1, \dots, b_{s-1}, b_1, \dots, b_k, \gamma_1, \dots, \gamma_k)$

move to position of $(s+1)$ 'st head:

write b_{s+1} and 'move head' according to γ_{s+1}

}
 ↓

Finally from state q^j
 $(b_1, \dots, b_k, b_1, \dots, b_k, \gamma_1, \dots, \gamma_k)$

move to state q^i
 (\dots)

Running time for simulation:

suppose takes t steps on w

- no tape can contain more than t new symbols (M writes at most one new (step))

simulating one step takes

- $O(|w| + kt)$ if no shift right call
- $O(k^2 t + |w|)$ if we need one or more shift right

so simulating t steps takes

$$O(k^2 t^2 + |w|t)$$