


BSG 3.48

$N = (V, A, c \geq 0, u, b, c)$

i) assume: some arcs have $u_{ij} = \infty$

claim: There exists a finite $(x_p, c < \infty \forall p \in A)$

optimal feasible flow

There is no cycle W in N with $c(W) < 0$
and $u_{ij} = \infty \forall ij \in A(W)$

Suppose there is a cycle W in N with $c(W) < 0$
and $u_{ij} = \infty \forall ij \in A(W)$.

Then W is a cycle of $N(x)$ for every
finite flow x so x cannot be optimal

Suppose that every cycle W of N with $c(W) < 0$
has at least one arc of finite capacity
and let y be a finite flow which is feasible
and has finite cost (we assume $|c_{ij}| < \infty \forall ij \in A$)

let x be an arbitrary feasible flow in N

Then $\exists \tilde{y} \in N(y)$ s.t. $x = y \oplus \tilde{y}$ when \tilde{y} is a circulation in $N(y)$

$c \cdot x = c \cdot y + c \cdot \tilde{y} \geq c \cdot y + \sum_{i=1}^r \delta(W_i) c(W_i)$ when

\tilde{y} can be decomposed into cycle flows along $W_1, \dots, W_1, \dots, W_p$
with $p \leq r$ and $c(W_i) < 0$ for $i \in [r]$ and
 $c(W_i) \geq 0$ for $i = r+1, \dots, p$ and $\delta(W_i)$ is the arcsum
capacity of W_i in $N(y)$

let $R = \left\lceil \sum_{i=1}^r \delta(w_i) c(w_i) \right\rceil$. Then $R < \infty$ so

we can extend y to a finite optimal feasible flow x using at most R iterations of the cycle cancelling algorithm. The flow x will be finite on all arcs.

ii) let $A' = \{ij \in A \mid u_{ij} < \infty\}$ and $V' = \{v \mid b(v) > 0\}$

$$K = \sum_{ij \in A'} u_{ij} + \sum_{v \in V'} b(v)$$

Assume N has no cycle w with $c(w) < 0$ and $u_{ij} = \infty \forall ij \in A(w)$.

Then by i) there exists a finite optimal flow x

consider a flow decomposition of x into

path flows along P_1, \dots, P_r of values $\delta_1, \dots, \delta_r$

and cycle flows along w_1, \dots, w_q of values β_1, \dots, β_q

$$\sum_{i=1}^r \delta_i = \sum_{v \in V'} b(v) \quad \text{as each } P_i \text{ starts in } V'$$

$$\sum_{j=1}^q \beta_j \leq \sum_{ij \in A'} u_{ij} \quad \text{as each } w_j \text{ intersects } A'$$

Hence $x_{ij} \leq K$ for every arc $ij \in A$

BJG 3.79

Let $N = (V, A, l \equiv 0, u, b, c)$ have a feasible flow x :

Prove that N has a feasible flow x for which

$$|A_x| \leq n - 1 \quad \text{when } n = |V| \text{ and}$$

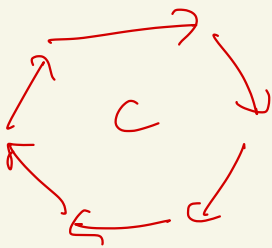
$$A_x = \{ij \mid 0 < x_{ij} < u_{ij}\}$$

Remark: we may assume that all flows are net flows
($x_{ij} \cdot x_{ji} = 0 \quad \forall$ 2-cycle $i \rightarrow j \rightarrow i$)

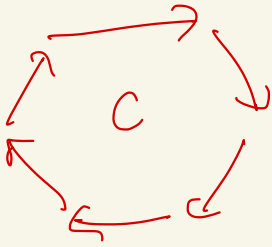
We will show that we can make x s.t.
 A_x has no cycle in the undirected sense

suppose A_x has a cycle C :

can A_x has a directed cycle C



C is also a cycle in $N(x)$
and its residual capacity is
 $\delta(C) = \min\{u_{ij} - x_{ij} \mid ij \in A(C)\}$

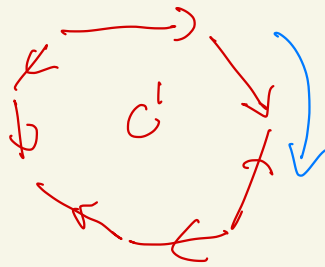


let $x \in x \oplus \delta(C) \cdot C$

then atleast one arc of C leaves A_x and no new arc

enters A_x since we had $x_{ij} > 0$ on all arcs in A_x before. Thus $|A_x|$ decreased and x is still feasible

Can 2 A_x have an oriented cycle but no directed cycle.



fix a direction for traversal of C

let $\delta_f = \min \{ u_{ij} - x_{ij} \mid ij \text{ forward cost orientation} \}$
 $\delta_b = \min \{ x_{ij} \mid ij \text{ backward cost orientation} \}$
 $\delta \in \min \{ \delta_f, \delta_b \}$

Let C_f be the directed cycle in $N(x)$ which corresponds to traversing C in the fixed direction.

Then $\delta(C_f) = \delta$ so $x^* \in x \oplus \delta: C_f$ is feasible and $|A_{x^*}| < |A_x|$

Both in Case 1 and in Case 2 we could decrease the number of arcs i_j with $0 < x_{ij} < u_{ij}$ so there exist a feasible flow x s.t. A_x has no cycle and thus $|A_x| \leq n-1 \quad \square$.

Algebra 8.7

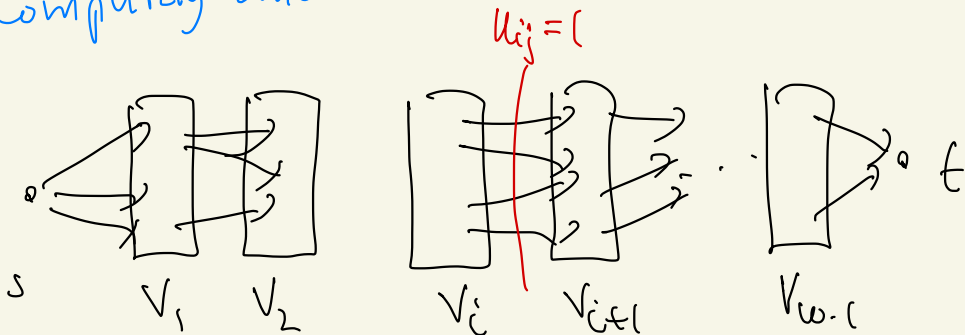
$$N = (V \cup \{s, t\}, A, c \equiv 0, u) \quad u_{ij} = 1 \text{ when } i \neq s, j \neq t$$

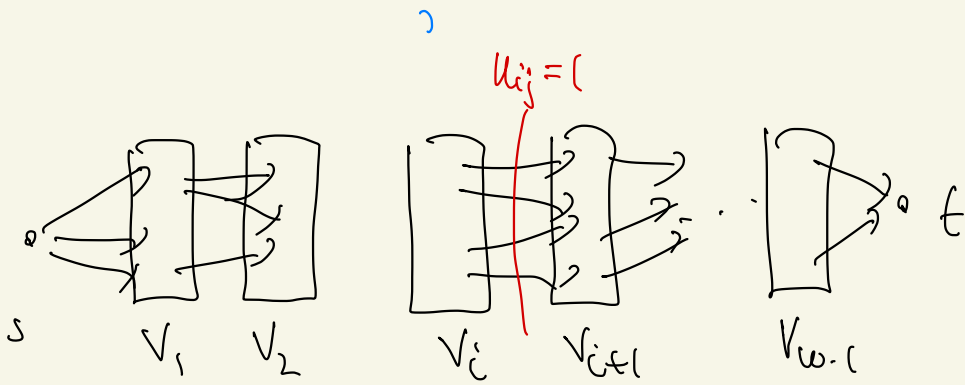
Q: does this change complexity of Dinic's algorithm?

A: We know from Exam 2020 prob. 4.3 that it does not change complexity. We prove it again below.

BjG lemma 3.7.2 still holds as we may assume all augmenting paths have capacity 1

[If $s \rightarrow t$ is an arc we start by filling it completely and consider N minus this arc]





Each of the cuts $(s \dots V_i, V_{i+1} \dots t)$ have capacity at most $|V_i| \cdot |V_{i+1}|$ so

(*) $|x^*| \leq |V_i| \cdot |V_{i+1}|$ for $i=1, 2, \dots, \omega-2$
 when x^* is a max flow

$$n = |V| \geq 2 + \sum_{i=1}^{\omega-2} |V_i| \geq 2 + \left\lfloor \frac{\omega-2}{2} \right\rfloor \cdot \sqrt{|x^*|}$$

\Downarrow

$$2n - 4 \geq (\omega - 2) \sqrt{|x^*|}$$

$$\Downarrow \quad \omega \leq \frac{2n - 4}{\sqrt{|x^*|}} + 2 \quad (\square)$$

so Lemma 3.7.3 in B)G holds with small change

proof of modified version of B/G Thm 3.7.4

- $q = \# \text{ plans in Dinic}$ $T = \lceil n^{2/3} \rceil$
- $0 \equiv x^{(0)}, x^{(1)}, \dots, x^{(q)}$ flows in algorithm
and $K = |x^{(q)}|$ (value of max flow)

- Choose j s.t. $K - |x^{(j)}| > T$
 $K - |x^{(j+1)}| \leq T$

- Then value of max flow x^* in $N(x^{(j)})$
is at least T so

$$\text{dist}_{N(x^{(j)})}(\text{set}) \leq \frac{2n-4}{\sqrt{n^{2/3}}} + 2 = O(n^{2/3})$$

- Rest of proof is original proof on
page 123 in B/G.

If one more vertex may be incident to arcs of
cap > 1 then we change $\lceil \square \rceil$ by a constant
so alg still has same complexity.

Almujer 8.8 $N = (V, \{s, t\}, A, \ell \geq 0, c)$

$u_{ij} \in \{1, 2, 3, 4\}$

Claim Dinic is still $O(n^{2/3}m)$:

Lemma 3.7.2: Each arc in a forest of augmenting paths before we delete it so $O(m)$ to find blocking flow

Lemma 3.7.3 Now $|X^*| \leq 4|N_c|/|N_{c^*}|$

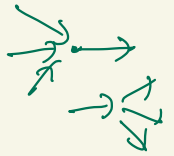
so $\min\{|N_c|, |N_{c^*}|\} \leq \frac{1}{2}\sqrt{|X^*|}$

\Rightarrow same bound on $\text{dist}(s, t)$ in O -notation

Remaining proof is same as B/G page 123

AH 8.10 Modified preflow-push als

for simple unit capacity networks:



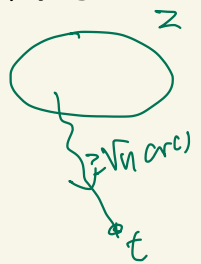
- No push/left performed on v if $h(v) \geq \sqrt{n}$

- a)
- Since $N(x)$ is also a unit cap network, there are no non-saturating pushes.
 - So at most $O(\sqrt{n})$ pushes along a given arc pq
 - Also each vertex is visited $O(\sqrt{n})$
 - Hence total work until $h(v) \geq \sqrt{n}$ holds for every v which has $b_x(v) < 0$ is $O(\sqrt{n} \cdot m) + O(\sqrt{n} \cdot n) = O(\sqrt{n} \cdot m)$

b) Claim: if x is flow at termination of above process then at most \sqrt{n} nodes of flow can reach t

P: let $Z = \{v \mid b_x(v) < 0, v \neq t\}$

Each $v \in Z$ has distance at least \sqrt{n} to t in $N(x)$ since h is a legal height function.



All flow from z to t in $N(x)$
must follow vertex-disjoint paths
(as $N(x)$ is unit capacity network) simple

let P_1, P_2, \dots, P_r be such paths

$$\text{then } r \leq \frac{n}{\sqrt{n}} = \sqrt{n}$$

so we can send at most \sqrt{n}
non-unit flows from z to t .

c) let x be preflow when modified pfp stops.

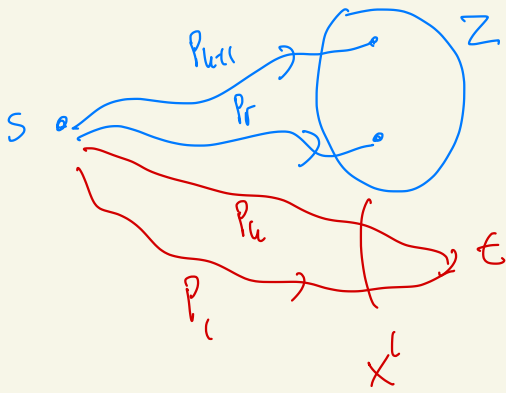
As N is a unit cap Network we can decompose
 x into unit path flows along $P_1, P_2, \dots, P_k, P_{k+1}, \dots, P_r$
and some cycles, when P_1, \dots, P_k are (s, t) -paths

We can find this decomposition in linear

time $O(n+m)$ since when we

extract a path or cycle, all its arcs

become empty



• Let x' be the ^{(s,t)-}flow formed by the union of the path flows along P_1, P_2, \dots, P_k

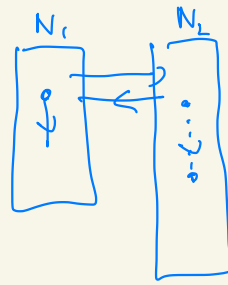
• Then the maximum flow value in $N(x')$ is at most \sqrt{n} by b)

• So we can find a max flow y in $N(x')$ in time $O(\sqrt{n}m)$

• adding y to x' gives a maximum flow in N .

Ahuja 8.18

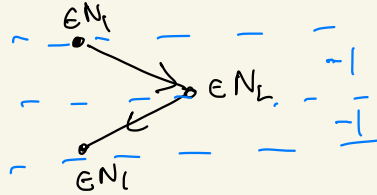
semi bipartite



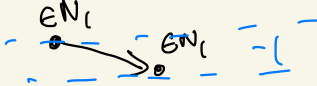
assume $n_1 \leq n_2$ show that

we can modify generic pfp so that it runs in time $O(n_1^2 m)$ time on semi-bipartite networks.

Consider the algorithm from section 8.3 when all pushes come in pairs



Now we also allow

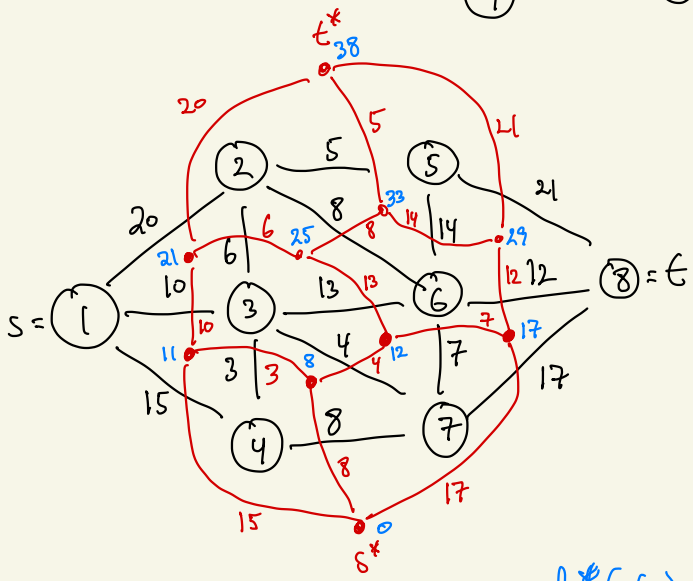
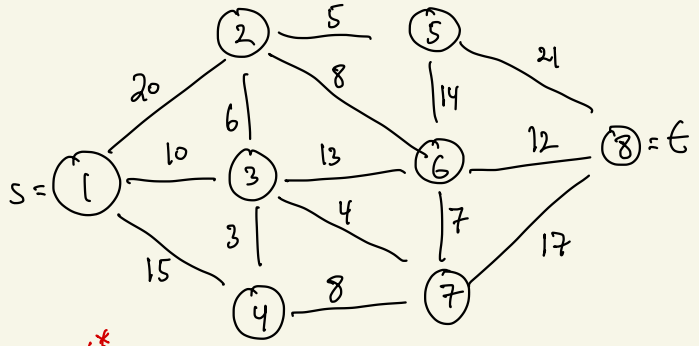


analysis still works as an unsaturated push now decreases $\Phi = \sum_{i \text{ active}} h(i)$ by at least 1 instead of at least 2 as in 8.3

Hence the analysis from 8.3 still works and we get that the algorithm runs in time $O(n_1^2 m)$ as before.

Ahuja 8.21

Goal: find a maximum flow in the undirected network given here, using the algorithm of section 8.4.

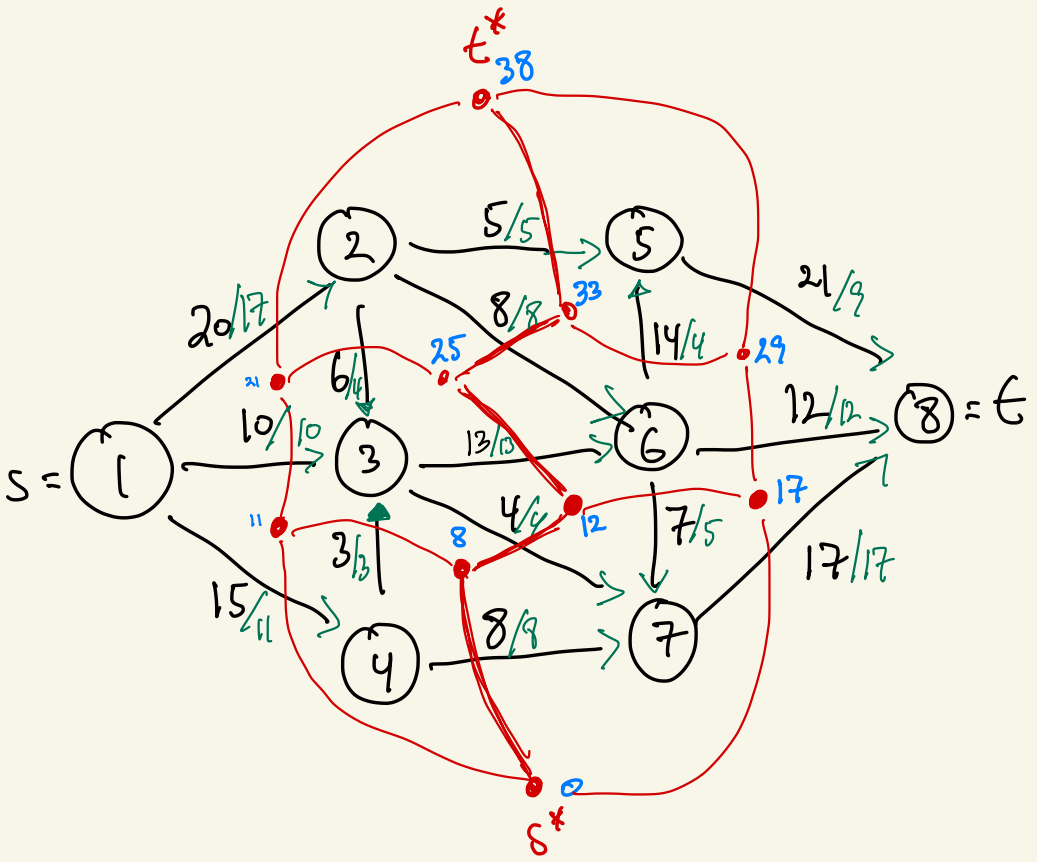


Dual of 6

$d^*(t) = d(s^*, t)$ indicated in blue $d^*(t) = 38$

so we know that the max flow value is 38 and we get such a flow by

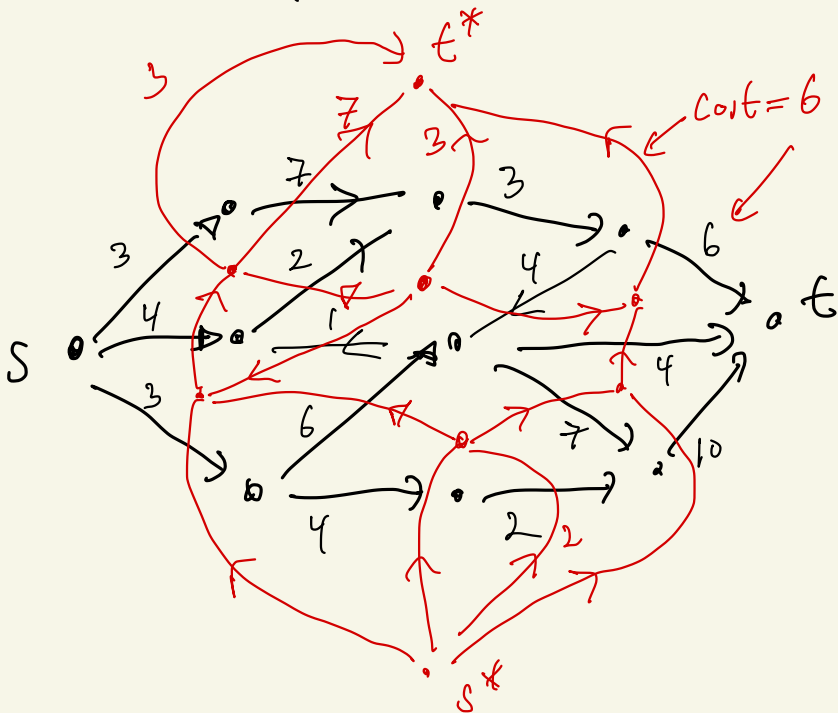
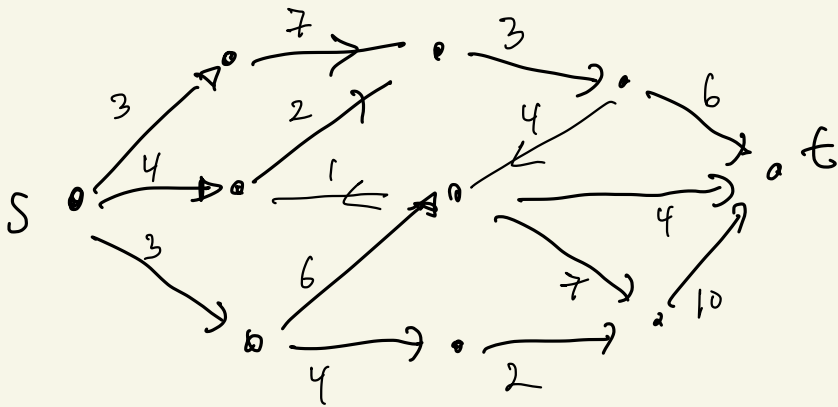
setting $x_{ij} = d^*(j) - d^*(i)$ when this is positive!

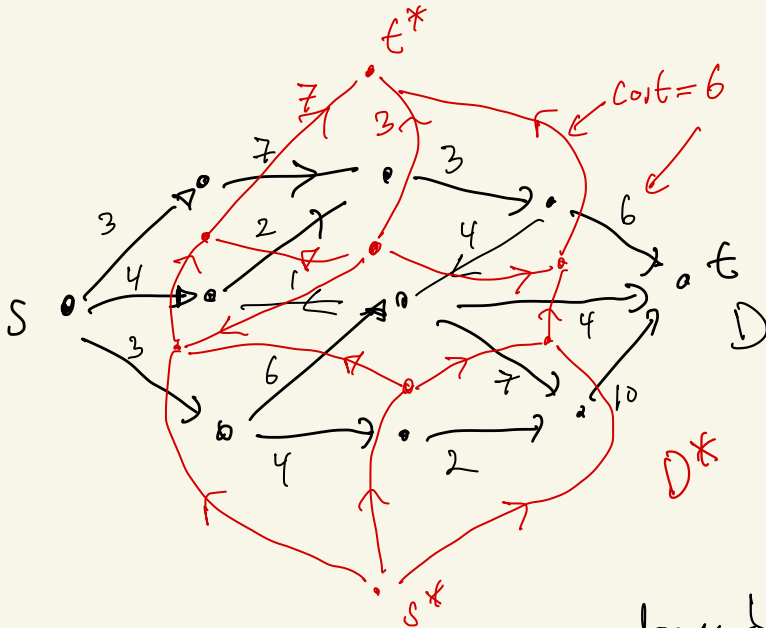


Ahuja 8.22

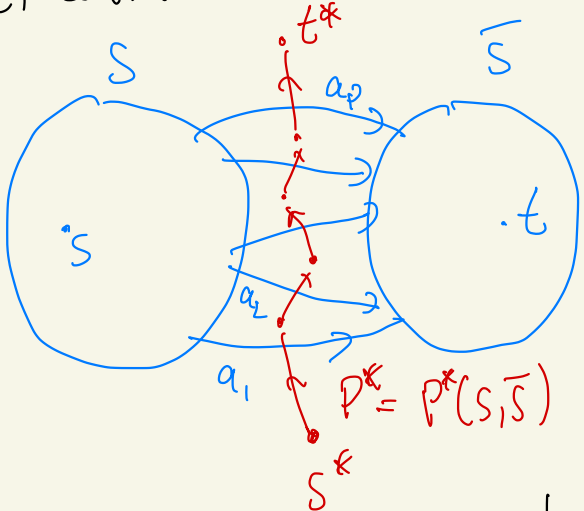
G is a planar (s, t) directed network
(s and t are on the outer face)

u_{ij} shown





Claim there is a 1-1 correspondence between (s, t) -cuts in D and (s^*, t^*) -paths in D^*



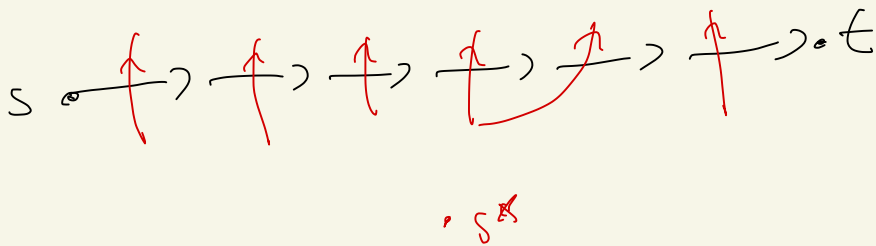
a_1, a_2, \dots, a_p are the $S \rightarrow \bar{S}$ arcs ordered after position in embeddings

Every (s^*, t^*) -path P^* gives a cut, namely the arcs in D intersected by the arcs in P^* and $\text{cost}(P) = u(S, \bar{S})$

Ahuja 8.23

claim: \min # of arcs in a directed (s, t) -path in D
 $= \max$ # arc-disjoint (s, t) -cuts in D

P: consider the dual D^* of D and note that every (s, t) -path in D defines an (s^*, t^*) -cut in D^* .



Hence

$$\begin{aligned} & \text{length of a shortest } (s, t)\text{-path in } D \\ &= \min \# \text{ arcs in an } (s^*, t^*)\text{-cut in } D^* \\ &= \max \# \text{ arc-disjoint } (s^*, t^*)\text{-paths in } D^* \\ &= \max \# \text{ arc-disjoint } (s, t)\text{-cuts in } D \end{aligned}$$

by Menger's theorem

Almuja 8.13

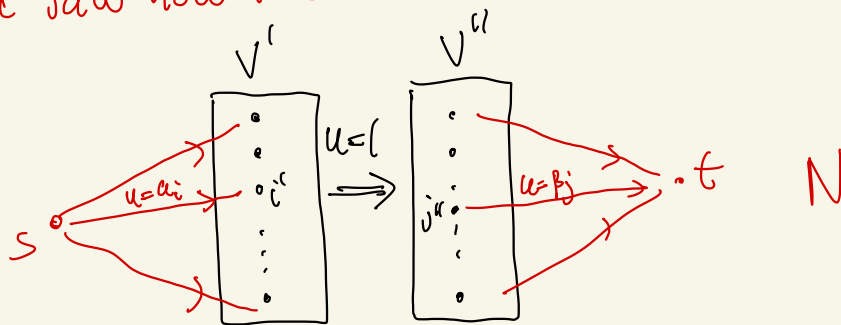
Given integers $\alpha_1, \dots, \alpha_n, \beta_1, \dots, \beta_n$ such that

$$\sum_{i=1}^n \alpha_i = \sum_{j=1}^n \beta_j \quad (*)$$

Question: Does there exist a digraph D on n vertices v_1, v_2, \dots, v_n with $d_D^+(v_i) = \alpha_i$ and $d_D^-(v_i) = \beta_i \quad \forall i \in [n]$

Solution: Note that D exists if and only if the complete digraph \overleftrightarrow{K}_n ($i, j \in A \quad \forall i \neq j$) has D as a subdigraph.

We saw how to check this in B/G Thm 3.11.5



N has an (s, t) -flow of value $\sum_{i=1}^n \alpha_i = \sum_{j=1}^n \beta_j$

\Downarrow
 D exists

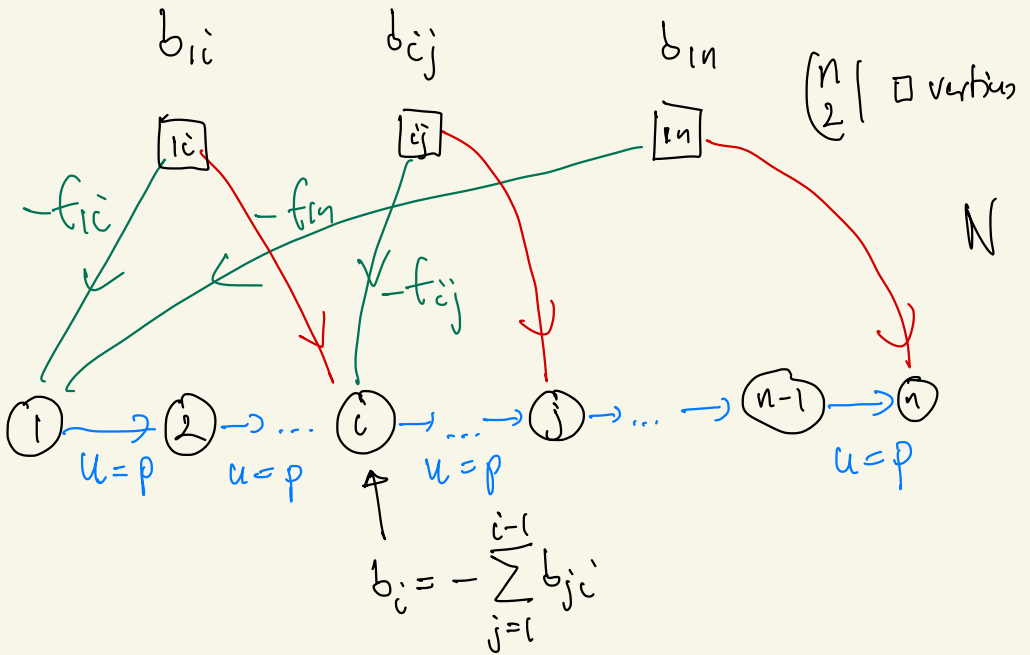
Ahuja 9.13 \approx BSG pages 130-131

b_{ij} = # passengers who wish to go from i to j

f_{ij} = ticket price for travel i to j

P = capacity of plane

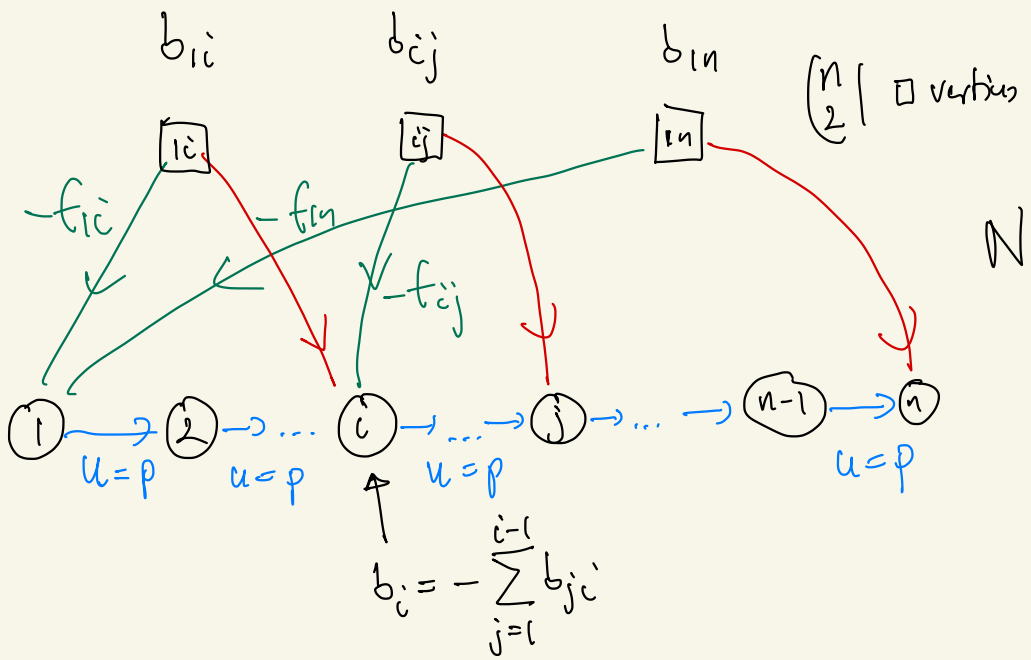
Goal: maximize income from accepted customers



green arcs \Leftrightarrow passengers taken

red arcs \Leftrightarrow passengers not taken

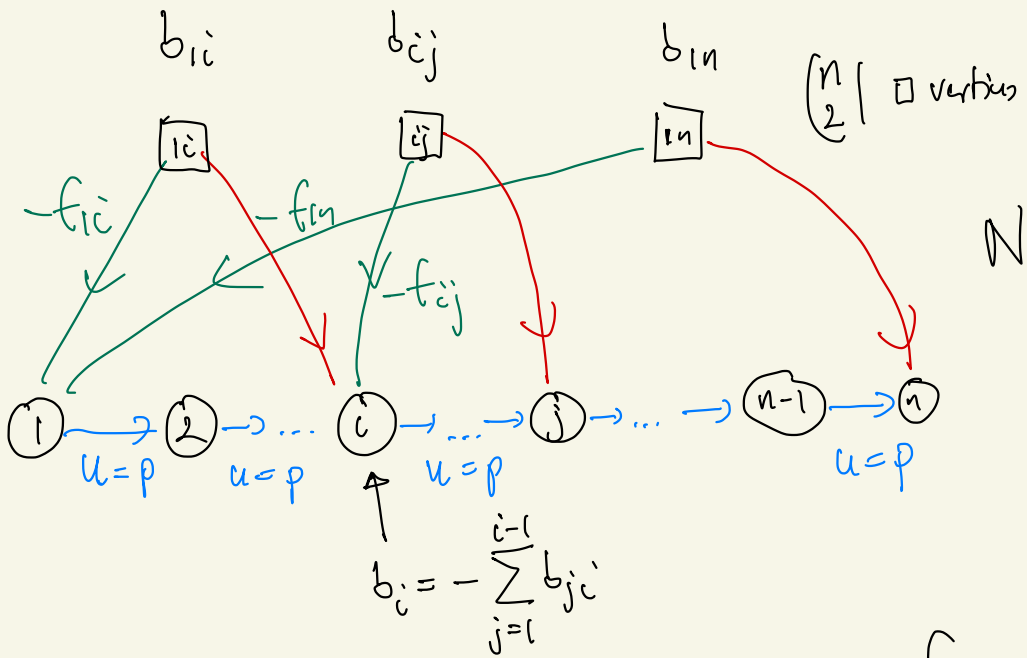
blue arcs model the capacity of the plane



Claim: $\{ \min c \times X \mid X \text{ feasible flow in } N \}$
 $= \text{max income we can obtain}$

\leq : each feasible flow X corresponds to legal passenger assignment and X_{ij} is the number of passengers from i to j that is taken.

So $c \times X = \sum_{1 \leq i < j \leq n} X_{ij} f_{ij} = \text{earnings from settings}$
 $f_{ij} = X_{ij} c$



\geq let t_{ij} denote # of passengers from i to j that we accept. Then we obtain a feasible flow x by setting

$$x_{(i)j_i} = t_{ij}, \quad x_{(i)j_j} = b_{ij} - t_{ij}, \quad x_{qst} = \sum_{\substack{a \leq q \\ b \geq st}} t_{ab}$$

and

$$-c x = \sum_{1 \leq i < j \leq n} t_{ij} f_{ij} = \text{income from assignment } t_{ij} \quad 1 \leq i < j \leq n$$

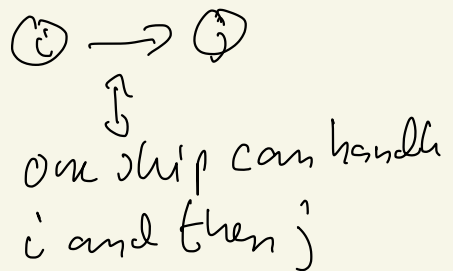
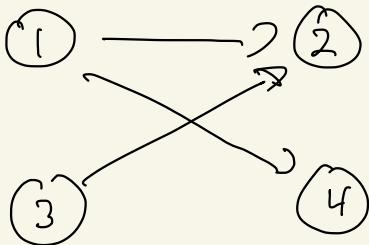
Alkha 9.14 Tanker scheduling
with startup costs.

Same data as in application 6.6

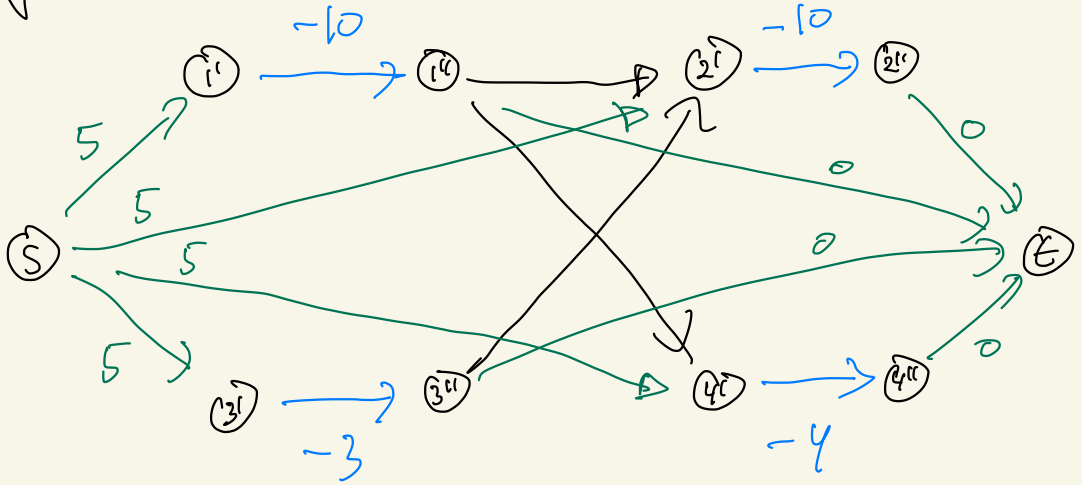
shipment	1	2	3	4
profit	10	10	3	4

Problem Assume it cost 5 units to use a ship and we do not have to handle all shipments.

Goal: maximize profit minus costs for ships.



N



all arcs have capacity 1

Claim (S, T) -flow of min cost gives a solution

P: We know (from earlier) that a solution with k ships corresponds to a flow of value k in N and the cost of such a flow is exactly the profit for that solution

Problem: How do we find an (s, t) -flow of minimum cost efficiently (value not prespecified)

Solution: use Buildup method

$x \leftarrow 0$ (zero flow)

while $\exists (s, t)$ -path P with $c(P) < 0$ in $N(x)$ do
augment x along P

let x be flow after termination of the loop

Then

- $\forall (s, t)$ -path P in $N(x)$: $c(P) \geq 0$ \square
- \forall cycle W in $N(x)$ $c(W) \geq 0$ \square

Claim $c x \leq c x'$ $\forall (s, t)$ -flow x'

P : if $|x'| \leq |x|$ then $c x \leq c x'$ as x was obtained from a min cost flow x'' with

$|x''| = |x|$ (by augmenting along zero or more paths) of negative cost

assume $|x| < |x'|$. Then there exist $\tilde{x} \in N(x)$
such that $x' = x \oplus \tilde{x}$ and

$$\begin{aligned} c x' &= c x + c \tilde{x} \\ &\geq c x \end{aligned}$$

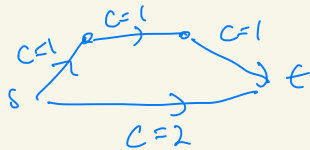
since \tilde{x} is a sum of paths and cycle flows in $N(x)$, all of which have non-negative cost by \square .

Almija 9.39

$N = (V, A, l \geq 0, u, b, c)$ c_{kk} minimum among all costs
 c_{pq} maximum - - -

- Q1 Is it possible that no min cost flow has $x_{kk} > 0$?
- Q2 Is it possible that every min cost flow has $x_{pq} > 0$?

Answer: Yes to both!



Every min cost (s,t)-flow
of value 1 sends
one unit along s-t

Almija 9.40

a) $N = (V, A, l \geq 0, u, b, c)$ all $b(e), u_{ij}$ even

Q: does there exist optimal feasible flow x
s.t. x_{ij} is even $\forall ij \in A$

Yes: $N \rightarrow N' = (V, A, l \geq 0, \frac{u}{2}, \frac{b}{2}, c)$

x' optimal feasible flow in N'

$x \in 2x'$ optimal and feasible in N

if π is a potential s.t. $c_{ij}^{\pi} \geq 0 \forall ij \in N'(x')$ s.t.
vino same π at $c_{ij}^{\pi} \geq 0 \forall ij \in N(x)$ du, x is optimal

$$b) \quad N = (V, A, l \equiv 0, u, b \equiv 0, c)$$

u_{ij} even $y \in N$ feasible circulation

Same method as in a)

Shows that there exists a
feasible circulation x with $x_{ij} \leq u_{ij}$
for all arcs ij

Atulja 9.41 $N = (V, A, l \equiv 0, u, b, c)$

x^* optimal solution and
 π potential s.t. $C_{ij}^\pi \geq 0 \quad \forall ij \in N(x^*)$

let $N^0 \subseteq N(x^*)$ consist of arc
with reduced cost = 0

• Suppose x^1 is another optimal feasible
flow on N .

• Thus $x^1 = x^* \oplus y$ where y is a
circulation in $N(x^*)$

and $C^\pi x^1 = C^\pi x^* + C^\pi y \geq 0$

$C^\pi y = 0$ and y decomposes into cycle flows
in $N(x^*)$

Since $C_{ij}^\pi \geq 0$ on all arcs each cycle w
in such a decomposition has $C^\pi(w) = 0$