


Algorithms for finding min cost flow

Thm 3.10 BCG = 9.1 is Always

A feasible flow x in $N = (V, A, l, u, b, c)$
is optimal (min cost) if and only
if $N(x)$ has no negative cycle.

This leads to

Cycle Cancelling algorithm

1. Find a feasible flow x in N (stop if no such)
2. while $N(x)$ has a negative cycle w
let δ be capacity of w
 $x \leftarrow x \oplus \delta(w)$
3. Return x

Theorem 3.10.2

If l, u, c and b are all integers valued

Then the cycle cancelling algorithm finds an optimal flow x in time

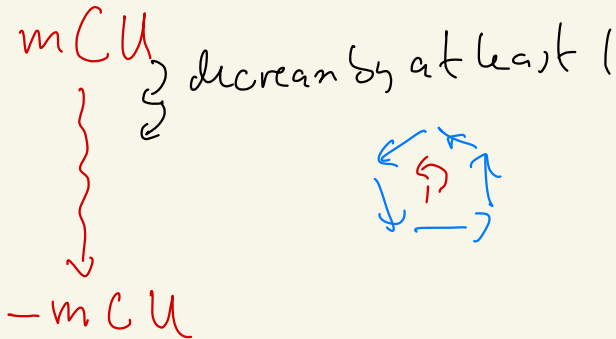
$O(nm^2CU)$ when $C = \max_{ij \in A} |c_{ij}|$

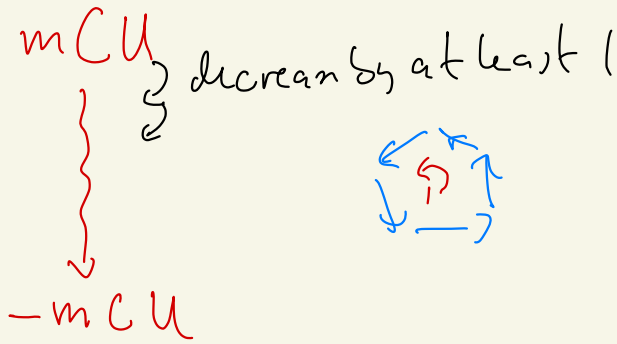
$U = \max_{ij \in A} u_{ij}$

• max possible cost of a flow in N is mCU

• min possible cost of a flow in N is $-mCU$

is $-mCU$





$O(mCU)$ iterations (finds a cycle in $N(x)$)

time to check for negative cycle
and find out if it exists $O(nm)$
by Bellman-Ford.

Total complexity

$$\begin{aligned}
 &O(nm) \cdot O(mCU) \\
 &= O(nm^2CU)
 \end{aligned}$$

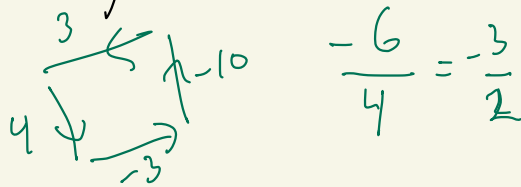
Theorem 3.10.3 Integrality theorem
for min cost flow

If l, u, b, c are all integer valued

then \exists an integer valued optimal flow X

The **mean cost** of a cycle W

is
$$\frac{c(W)}{|A(W)|}$$



Theorem If the cycle cancelling algorithm always augments maximally along

a cycle of minimum mean cost

then it runs in time $O(n^2 m^3 \log n)$

even if some arcs have irrational data (l, u or c)

Theorem 3.10.5 (Buildup theorem)

Let x be an optimal flow with respect to $b = b_x$ (and $l \leq x \leq u$)

If P is a shortest (p, q) -path in $N(x)$ and $\alpha \leq \delta(P)$

Then the flow $x' = x \oplus \alpha P$ is optimal w.r.t. the balance functions!

$$\text{with } b'(v) = \begin{cases} b(v) & \text{if } v \neq p, q \\ b(v) + \alpha & \text{if } v = p \\ b(v) - \alpha & \text{if } v = q \end{cases}$$

Proof: It suffices to show that

$N(x')$ has no negative cycle

Suppose W negative cycle in $N(x')$

Recall that each arc in $N(x')$

is either also in $N(x)$ or

it is opposite to an arc $i \rightarrow j$ in $N(x)$

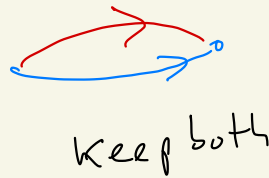
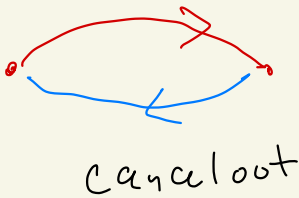
and then P contains the arc $i \rightarrow j$

Consider the multigraph H

defined by $H = (V, \tilde{A})$ when

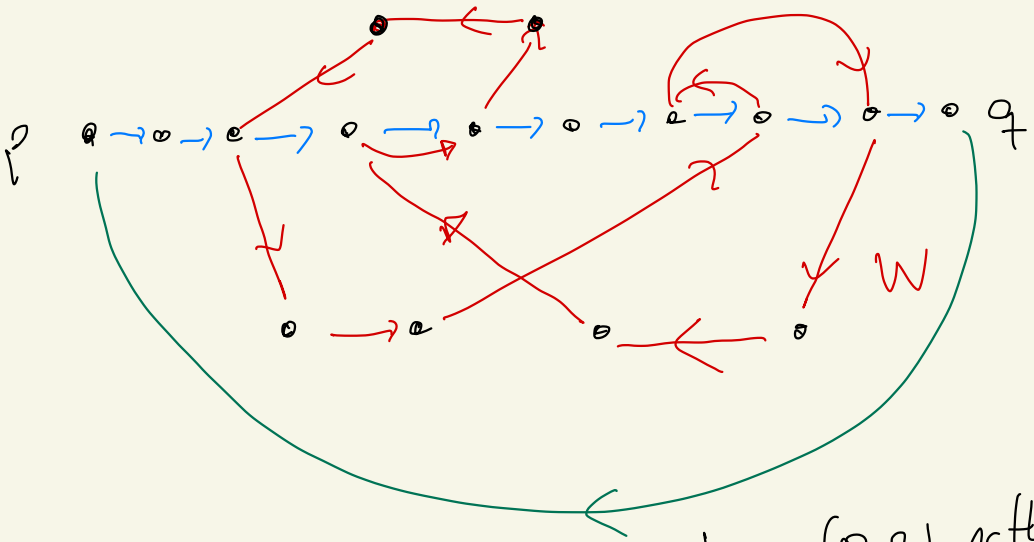
\tilde{A} :

W
 P



$H + |W|P$ is eulerian

$H + \lfloor \frac{q}{p} \rfloor$ is eulerian



Hence H decomposes into a (p, q) -path P and some arc-disjoint cycles

W_1, W_2, \dots, W_k (by BGC ex 3.8)

• Each W_i is a cycle in $N(x)$

Cost of opposite arcs cancel out
($c_{ij} = -c_{ji}$) so as $c(W) < 0$

$$\begin{aligned} c(P) &> c(P) + c(W) \\ &= c(P') + \sum_{i=1}^k c(W_i) \\ &\geq c(P') \end{aligned}$$

as each $c(W_i) \geq 0$ by optimality of x

Thus $c(P) > c(P')$ } as P was a
shortest
 (p, q) -path

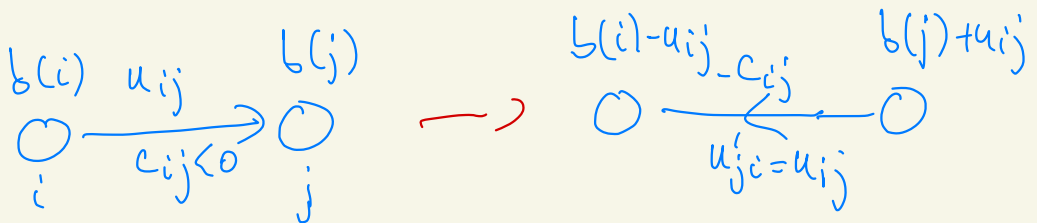
BJG exercin 3.49 and
Aluja page 40:

We can always modify a network
 $N = (V, A, l \equiv 0, u, b, c)$ with $c_{ij} < 0$
 for some arc $ij \in A$ to a network

$$N' = (V, A', l \equiv 0, u', b', c')$$

so that given an optimal flow x'
 in N' we can obtain an optimal flow
 x in N

Reverse arc with $c_{ij} < 0$:



$$x_{ij} = u_{ij} - x'_{ij} \quad \leftarrow \quad x'_{ij}$$

Congruence we may assume
that $c_{ij} \geq 0 \quad \forall ij \in A$

Then $x \equiv 0$ is optimal (min cost
among all flows
with $b_x(v) = 0 \quad \forall v$)
Since $N(x) = N$ has no
negative cycle

For a given optimal flow x and
 $N = (V, A, l \equiv 0, u, b, c)$ set

$$U_x = \{v \mid b_x(v) < b(v)\}$$

$$Z_x = \{v \mid b_x(v) > b(v)\}$$

note $U_x = \emptyset \Leftrightarrow Z_x = \emptyset$

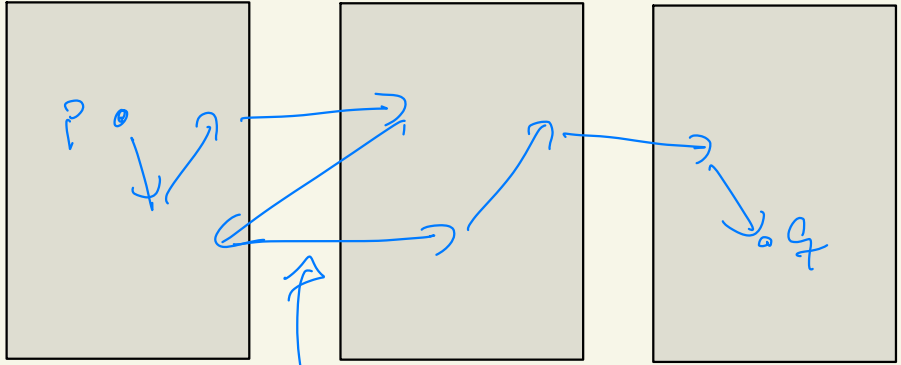
and then x is feasible and
optimal flow in N

For a given optimal x :

$$b_x(r) < b(r)$$

$$b_x(r) = b(r)$$

$$b_x(r) > b(r)$$



U_x

shortest (p, q) -path

Z_x

Buildup algorithm:

1. $x_{ij} \leftarrow 0 \forall ij \in A$; Find U_x, Z_x
2. If $U_x = \emptyset$ go to 8.
3. If $\nexists (U_x, Z_x)$ -path in $N(x)$ go to 9.
4. Choose $p \in U_x, q \in Z_x$ s.t. $N(x)$ has a (p, q) -path
5. Find a shortest (p, q) -path P in $N(x)$
6. $\varepsilon \leftarrow \min \{ \delta(P), b(p) - b_x(p), b_x(q) - b(q) \}$
7. $x \leftarrow x \oplus \varepsilon P$; Find new U_x, Z_x and go to 2
8. Return x
9. Return 'no feasible solution'

Theorem 3.10.6

Let $N = (V, A, l \equiv 0, u, b, c)$ have integer data and $c_{ij} \geq 0 \forall ij \in A$

Then the buildop algorithm constructs a minimum cost flow in N or determines that no feasible flow exists in N .

The running time is $O(n^2 m M)$

where $M = \max_{v \in V} |b(v)|$

- No vertex has its balance increased more than M times.
- To Find new shortest path takes $O(nm)$
- At most $n \cdot M$ augmentation steps
 $\Rightarrow O(n^2 m M)$

Why does there exist a
 (u_x, z_x) -path in $N(x)$ if
 N has a feasible flow?

Suppose y is feasible in $N = (V, A, l \leq 0, u, b, c)$
 $b_y(u) = b(u) \forall u$

$y = x \oplus x''$ x'' flow in $N(x)$

$$b(u) = b_y(u) = b_x(u) + b_{x''}(u)$$

$$\text{For } p \in U_x : b_{x''}(p) \geq 0$$

$$z \in Z_x : b_{x''}(z) < 0$$

$$b(v) = b_y(v) = b_x(v) + b_{x''}(v)$$

$$\text{For } p \in U_x : b_{x''}(p) \geq 0$$

$$z \in Z_x : b_{x''}(z) < 0$$

$$v \notin U_x \cup Z_x : b_{x''}(v) = 0$$

Decompose x'' into path + cycle flow

all paths start in U_x and end
in Z_x

In particular \exists a (U_x, Z_x) -path !!
in $N(x)$