

The Max Flow Problem

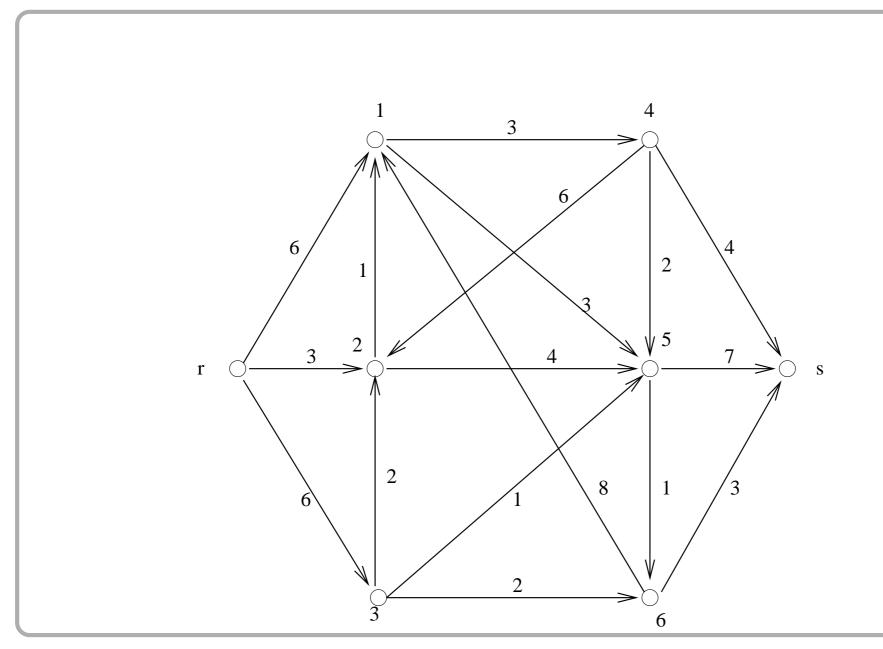
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Max-Flow Terminology

- We consider a digraph G = (V, E) which for each e has a capacity $u_e \in R_+$.
- Furthermore two "special" vertices r and s are given; these are called resp. the source and the sink.
- A flow in G is a function $x: E \to R_+$ satisfying:

$$\forall v \in V \setminus \{r, s\} : \sum_{(w,v) \in E} x_{wv} - \sum_{(w,v) \in E} x_{vw} = 0$$

$$\forall (v, w) \in E : 0 \leq x_{vw} \leq u_{vw}$$





Flow

For a flow we define:

$$f_x(v) = \sum_{(w,v)\in E} x_{wv} - \sum_{(w,v)\in E} x_{vw}$$

- $f_x(v)$ is the net flow into v or the excess for x in v.
- $f_x(s)$ is called the value of x.





Math. Programming Model of Max Flow

$$\max f_x(s)$$

$$f_x(v) = 0 \qquad v \in V \setminus \{r, s\}$$

$$0 \le x_e \le u_e \qquad e \in E$$

$$x_e \text{ integral, } e \in E$$



Max Flow and cuts

• We now consider $R \subset V$. $\delta(R)$ is the set of edges incident from a vertex in R to a vertex in $V \setminus R$. $\delta(R)$ is also called the cut generated by R:

$$\delta(R) = \{(v, w) \in E \mid v \in R, w \in V \setminus R\}$$

- R is an r,s-cut if $r \in R$ and $s \notin R$.
- The capacity of the cut R is defined as:

$$u(\delta(R)) = \sum_{(u,w)\in E, v\in R, w\in V\setminus R} u_{vw}$$





Relationship between flows and cuts

- Proposition: For any (r,s)-cut $\delta(R)$ and any (r,s)-flow x we have: $x(\delta(R)) x(\delta(\bar{R})) = f_x(s)$
- Corollary: For any feasible (r, s)-flow x and any (r, s)-cut $\delta(R)$, we have: $f_x(s) \le u(\delta(R))$.



The Residual graph

- Suppose that x is a flow in G. The residual graph shows how flow excess can be moved in G given that the flow x is already present.
- The residual graph G_x for G wrt. x is defined by:

$$V(G_x) = V$$

$$E(G_x) = \{(v, w) \mid (v, w) \in E \land x_{vw} < u_{vw}\} \cup \{(w, v) \mid (v, w) \in E \land x_{vw} > 0\}$$



Incrementing and augmenting path

- A path is called x-incrementing if for every forward arc e x_e < u_e and for every backward arc $x_e > 0$.
- A x-incrementing path from r to s is called x-augmenting.





Algorithm for the Max-Flow Problem

- 1. Utilize spare capacity
- 2. dipaths in the residual path
- 3. flow augmenting path





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Initialize x_{vw} \leftarrow 0 for all (v,w) \in E

repeat

construct G_x

find an augmenting path

if (s \text{ is reached})

augment x as much as possible

until (s \text{ is not reachable from } r \text{ in } G_x)
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Finding an augmenting path

Input: The network G = (V, E, u) and the current feasible flow x.

Output: An augmenting path from r to s and the capacity for the flow augmentation.

Initialize: all vertices are unlabeled;

$$Q := \{r\}, S := \emptyset, p[.] := 0;$$

$$u_{\text{max}}[v] := +\infty \text{ for } v \in G$$





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while Q \neq \emptyset and s is not labeled yet
    select a v \in Q and scan \{(v, w) \in E\} \cup \{(w, v) \in E\}
         if (v, w) \in E and x_{vw} < u_{vw} and w unlabeled:
              label w; Q := Q \cup \{w\}; p[w] := v
              u_{\max}[w] := \min\{u_{\max}[v], u_{vw} - x_{vw}\}
         if (w, v) \in E and x_{wv} > 0 and w unlabeled:
              label w; Q := Q \cup \{w\}; p[w] := v
             u_{\max}[w] := \min\{u_{\max}[v], x_{wv}\}
    Q := Q \setminus \{v\}; S := S \cup \{v\}
    if s is labeled then the r-s-aug. path is given
         by the predecessor index p[].
         Otherwise no r-s-augmenting path exists.
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Augmenting a feasible flow x

Input: The network G = (V, E, u), the current feasible flow x, an augmenting path P from r to s in G_x and the x-width of P.

Output: An "updated" feasible flow x'.

- for $(v, w) \in P : (v, w) \in E : x'_{vw} = x_{vw} + u_{\max}[s]$
- for $(v, w) \in P : (w, v) \in E : x'_{wv} = x_{wv} u_{\text{max}}[s]$
- for all other $(v, w) \in E : x'_{vw} = x_{vw}$





Max Flow - Min Cut Theorem

Given a network G = (V, E, U) and a current feasible flow x. The following 3 statements are equivalent:

- x is a maximum flow in G.
- A flow augmenting r-s-path does not exist (an r-s-dipath in G_x).
- An r, s-cut R exists with capacity equal to the value of x, ie. $u(R) = f_x(s)$.





- We call an augmenting path from r to s shortest if it has the minimum possible number of arcs.
- The augmenting path algorithm with a breadth-first search solves the maximum flow problem in $O(nm^2)$.
- Breadth-first can easily be established using a queue.

