DM545 Linear and Integer Programming

Lecture 3 The Simplex Method

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Outline

1. Simplex Method

Standard Form Basic Feasible Solutions Algorithm Tableaux and Dictionaries

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A Numerical Example

$$\max \sum_{\substack{j=1 \\ j=1}^{n} c_j x_j}^{n} c_j x_j \le b_i, \ i = 1, \dots, m$$
$$x_j \ge 0, \ j = 1, \dots, n$$

 $\begin{array}{ll} \max \ \mathbf{c}^{\mathsf{T}}\mathbf{x} \\ A\mathbf{x} \ \leq \ \mathbf{b} \\ \mathbf{x} \ \geq \ \mathbf{0} \end{array}$

 $\max \begin{bmatrix} 6 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ $\begin{bmatrix} 5 & 10 \\ 4 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \le \begin{bmatrix} 60 \\ 40 \end{bmatrix}$ $x_1, x_2 \ge 0$

 $\mathbf{x} \in \mathbb{R}^{n}, \mathbf{c} \in \mathbb{R}^{n}, A \in \mathbb{R}^{m imes n}, \mathbf{b} \in \mathbb{R}^{m}$

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1. Simplex Method Standard Form

Basic Feasible Solutions Algorithm Tableaux and Dictionaries

Standard Form

Every LP problem can be converted in the form:

 $\begin{array}{l} \max \, \mathbf{c}^{\mathsf{T}} \mathbf{x} \\ A \mathbf{x} \, \leq \, \mathbf{b} \\ \mathbf{x} \, \in \, \mathbb{R}^{n} \end{array} \\ \mathbf{c} \in \mathbb{R}^{n}, A \in \mathbb{R}^{m \times n}, \mathbf{b} \in \mathbb{R}^{m} \end{array}$

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- if equations, then put two constraints, $ax \le b$ and $ax \ge b$
- if $ax \ge b$ then $-ax \le -b$
- if min $c^T x$ then max $(-c^T x)$

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and then be put in standard (or equational) form

 $\begin{array}{l} \max \ \mathbf{c}^{\mathsf{T}} \mathbf{x} \\ A \mathbf{x} \ = \ \mathbf{b} \\ \mathbf{x} \ \ge \ \mathbf{0} \\ \mathbf{x} \in \mathbb{R}^{n}, \mathbf{c} \in \mathbb{R}^{n}, A \in \mathbb{R}^{m \times n}, \mathbf{b} \in \mathbb{R}^{m} \end{array}$

- 1. "=" constraints
- 2. $\mathbf{x} \ge \mathbf{0}$ nonnegativity constraints

4. max

Every LP problem can be transformed in eq. std. form

1. introduce slack variables (or surplus)

 $5x_1 + 10x_2 + x_3 = 60$ $4x_1 + 4x_2 + x_4 = 40$

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 then $\begin{array}{c} x_1 = x_1' - x_1'' \\ x_1' \ge 0 \\ x_1'' \ge 0 \end{array}$

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- 4. min $c^T x \equiv \max(-c^T x)$

LP in $n \times m$ converted into LP with at most (m + 2n) variables and m equations (n # original variables, m # constraints)

Geometry of LP in Eq. Std. Form

$$\max\{\mathbf{c}^{\mathsf{T}}\mathbf{x} \mid A\mathbf{x} = \mathbf{b}, \mathbf{x} \ge \mathbf{0}\}$$

From linear algebra:

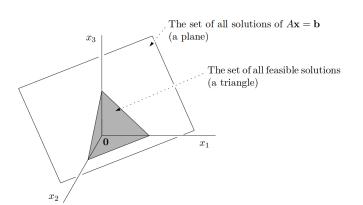
- the set of solutions of $A\mathbf{x} = \mathbf{b}$ is an affine space (plane not passing through the origin).
- $x \geq 0$ nonegative orthant (octant in $\mathbb{R}^3)$

Geometry of LP in Eq. Std. Form

 $\max\{\mathbf{c}^{\mathsf{T}}\mathbf{x} \mid A\mathbf{x} = \mathbf{b}, \mathbf{x} > \mathbf{0}\}$

From linear algebra:

- the set of solutions of Ax = b is an affine space (plane not passing through the origin).
- $x \geq 0$ nonegative orthant (octant in $\mathbb{R}^3)$



In \mathbb{R}^3 :

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- We assume $n \ge m$ and

 $\operatorname{rank}([A \mid \mathbf{b}]) = \operatorname{rank}(A) = m$

, ie, rows of A are linearly independent otherwise, remove linear dependent rows

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Basic Feasible Solutions

Basic feasible solutions are the vertices of the feasible region:



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Definition

 $\mathbf{x} \in \mathbb{R}^n$ is a basic feasible solution of the linear program $\max{\{\mathbf{c}^T \mathbf{x} \mid A\mathbf{x} = \mathbf{b}, \mathbf{x} \ge \mathbf{0}\}}$ for an index set *B* if:

- $x_j = 0 \ \forall j \notin B$
- the square matrix A_B is nonsingular, ie, all columns indexed by B are lin. indep.
- $\mathbf{x}_B = A_B^{-1} \mathbf{b}$ is nonnegative, ie, $\mathbf{x}_B \ge 0$ (feasibility)

We call x_j for $j \in B$ basic variables and remaining variables nonbasic variables.

Theorem

A basic feasible solution is uniquely determined by the set B.

Proof:

$$Ax = A_B x_B + A_N x_N = b$$

$$x_B + A_B^{-1} A_N x_N = A_B^{-1} b$$

$$x_B = A_B^{-1} b$$

$$A_B \text{ is singular hence one solution}$$

Note: we call B a (feasible) basis

Theorem

Let P be a (convex) polyhedron from LP in std. form. For a point $v \in P$ the following are equivalent:

- (i) v is an extreme point (vertex) of P
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Proof. consequence of previous theorem and fundamental theorem of linear programming

Idea for solution method: examine all basic solutions. There are finitely many: $\binom{m+n}{m}$. However, if n = m then $\binom{2m}{m} \approx 4^m$.

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Simplex Method

$$\max \quad z = \begin{bmatrix} 6 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
$$\begin{bmatrix} 5 & 10 & 1 & 0 \\ 4 & 4 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 60 \\ 40 \end{bmatrix}$$
$$x_1, x_2, x_3, x_4 \ge 0$$

Canonical eq. std. form: one decision variable is isolated in each constraint and does not appear in the other constraints nor in the obj. func. and *b* terms are positive

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It gives immediately a basic feasible solution:

 $x_1 = 0, x_2 = 0, x_3 = 60, x_4 = 40$

Is it optimal?

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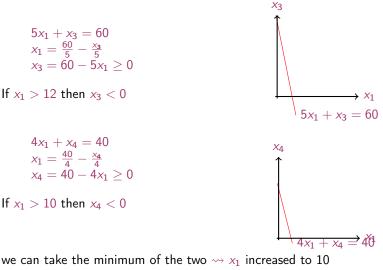
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Is it optimal? Look at signs in $z \rightsquigarrow$ if positive then an increase would improve.

Let's try to increase a promising variable, ie, $x_{\rm l},$ one with positive coefficient in z



 x_4 exits the basis and x_1 enters

Simplex Tableau

First simplex tableau:



Simplex Tableau

First simplex tableau:

we want to reach this new tableau

Simplex Tableau

First simplex tableau:

	x_1	<i>x</i> ₂	<i>x</i> 3	<i>x</i> ₄	- <i>z</i> 0 0	Ь
<i>X</i> 3	5	10	1	0	0	60
<i>x</i> 4	4	4	0	1	0	40
	6	8	0	0	1	0

we want to reach this new tableau

Pivot operation:

1. Choose pivot:

column: one s with positive coefficient in obj. func. row: ratio between coefficient b and pivot column: choose the one with smallest ratio:

$$heta = \min_i \left\{ rac{b_i}{a_{is}} : a_{is} > 0
ight\}, \qquad egin{array}{c} heta & ext{increase value} \ heta & ext{of entering var.} \end{array}$$

2. elementary row operations to update the tableau

- x_4 leaves the basis, x_1 enters the basis
 - Divide pivot row by pivot
 - Send to zero the coefficient in the pivot column of the first row
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 												ъI
I'=I-5II' II'=II/4	 	0 1	 	5 1	 	1 0	 	-5/4 1/4	 	0 0	 	10 10
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From the last row we read: $2x_2 - 3/2x_4 - z = -60$, that is: $z = 60 + 2x_2 - 3/2x_4$. Since x_2 and x_4 are nonbasic we have z = 60 and $x_1 = 10, x_2 = 0, x_3 = 10, x_4 = 0$.

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Definition (Reduced costs)

We call reduced costs the coefficients in the objective function of the nonbasic variables, \bar{c}_N

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Proposition (Optimality Condition)

The basic feasible solution is optimal when the reduced costs in the corresponding simplex tableau are nonpositive, ie, such that:

$\bar{c}_N \leq 0$

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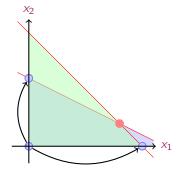
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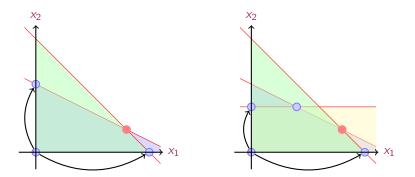
Proof: Let z_0 be the obj value when $\bar{c}_N \leq 0$. For any other feasible solution $\tilde{\mathbf{x}}$ we have:

$$\mathbf{\tilde{x}}_N \ge 0$$
 and $\mathbf{c}^T \mathbf{\tilde{x}} = z_0 + \mathbf{\bar{c}}_N^T \mathbf{\tilde{x}}_N \le z_0$

Graphical Representation



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$$\max \sum_{\substack{j=1 \\ n \\ j=1}}^{n} c_j x_j$$
$$\sum_{\substack{j=1 \\ x_j \geq 0, j=1,\ldots,n}}^{n} a_{ij} x_j \leq b_i, i = 1,\ldots, m$$

$$\max \sum_{\substack{j=1 \\ j=1}^{n} c_{j}x_{j}}^{n} c_{j}x_{j} \leq b_{i}, \ i = 1, \dots, m \\ x_{j} \geq 0, \ j = 1, \dots, n \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_$$

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$$x_{n+i} = b_i - \sum_{j=1}^n a_{ij} x_j, \quad i = 1, \dots, m$$
$$z = \sum_{j=1}^n c_j x_j$$

Tableau

Dictionary

$$\begin{bmatrix} I & \bar{A}_{N} & 0 & \bar{b} \\ 0 & \bar{c}_{N} & 1 & -\bar{d} \end{bmatrix}$$

$$\begin{aligned} x_r &= \bar{b}_r - \sum_{s \notin B} \bar{a}_{rs} x_s, \quad r \in B \\ z &= \bar{d} + \sum_{s \notin B} \bar{c}_s x_s \end{aligned}$$

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pivot operations in dictionary form: choose col s with r.c. > 0 choose row with min{ $-\bar{b}_i/\bar{a}_{is} \mid a_{is} < 0, i = 1, \ldots, m$ } update: express entering variable and substitute in other rows

Example

$$x_3 = 60 - 5x_1 - 10x_2$$

$$x_4 = 40 - 4x_1 - 4x_2$$

$$z = + 6x_1 + 8x_2$$

Example

After 2 iterations:

$$x_3 = 60 - 5x_1 - 10x_2$$

$$x_4 = 40 - 4x_1 - 4x_2$$

$$z = + 6x_1 + 8x_2$$

Summary

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