DM545 Linear and Integer Programming

### Lecture 3 The Simplex Method

### Marco Chiarandini

Department of Mathematics & Computer Science University of Southern Denmark

# Outline

### 1. Simplex Method

Standard Form Basic Feasible Solutions Algorithm Tableaux and Dictionaries

# Outline

### 1. Simplex Method

Standard Form Basic Feasible Solutions Algorithm Tableaux and Dictionaries

# A Numerical Example

$$\max \sum_{\substack{j=1 \\ j=1}^{n} c_j x_j}^{n} c_j x_j \le b_i, \ i = 1, \dots, m$$
$$x_j \ge 0, \ j = 1, \dots, n$$

 $\begin{array}{ll} \max \ \mathbf{c}^{\mathsf{T}}\mathbf{x} \\ A\mathbf{x} \ \leq \ \mathbf{b} \\ \mathbf{x} \ \geq \ \mathbf{0} \end{array}$ 

 $\max \begin{bmatrix} 6 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  $\begin{bmatrix} 5 & 10 \\ 4 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \le \begin{bmatrix} 60 \\ 40 \end{bmatrix}$  $x_1, x_2 \ge 0$ 

 $\mathbf{x} \in \mathbb{R}^{n}, \mathbf{c} \in \mathbb{R}^{n}, A \in \mathbb{R}^{m imes n}, \mathbf{b} \in \mathbb{R}^{m}$ 

# Outline

### 1. Simplex Method Standard Form

Basic Feasible Solutions Algorithm Tableaux and Dictionaries

# Standard Form

Every LP problem can be converted in the form:

 $\begin{array}{l} \max \, \mathbf{c}^{\mathsf{T}} \mathbf{x} \\ A \mathbf{x} \, \leq \, \mathbf{b} \\ \mathbf{x} \, \in \, \mathbb{R}^{n} \end{array} \\ \mathbf{c} \in \mathbb{R}^{n}, A \in \mathbb{R}^{m \times n}, \mathbf{b} \in \mathbb{R}^{m} \end{array}$ 

# Standard Form

Every LP problem can be converted in the form:

 $\begin{array}{l} \max \ \mathbf{c}^{T}\mathbf{x} \\ A\mathbf{x} \leq \mathbf{b} \\ \mathbf{x} \in \mathbb{R}^{n} \end{array}$  $\mathbf{c} \in \mathbb{R}^{n}, A \in \mathbb{R}^{m \times n}, \mathbf{b} \in \mathbb{R}^{m} \end{array}$ 

- if equations, then put two constraints,  $ax \le b$  and  $ax \ge b$
- if  $ax \ge b$  then  $-ax \le -b$
- if min  $c^T x$  then max $(-c^T x)$

# Standard Form

Every LP problem can be converted in the form:

$$\begin{array}{l} \max \mathbf{c}^{\mathsf{T}} \mathbf{x} \\ A \mathbf{x} \leq \mathbf{b} \\ \mathbf{x} \in \mathbb{R}^{n} \end{array} \bullet \text{ if equations, then put two constraints, } ax \leq b \text{ and } ax \geq b \\ \bullet \text{ if } ax \geq b \text{ then } -ax \leq -b \\ \mathbf{c} \in \mathbb{R}^{n}, A \in \mathbb{R}^{m \times n}, \mathbf{b} \in \mathbb{R}^{m} \end{array} \bullet \text{ if } \min c^{\mathsf{T}} x \text{ then } \max(-c^{\mathsf{T}} x) \end{array}$$

and then be put in standard (or equational) form

 $\begin{array}{l} \max \ \mathbf{c}^{\mathsf{T}} \mathbf{x} \\ A \mathbf{x} \ = \ \mathbf{b} \\ \mathbf{x} \ \ge \ \mathbf{0} \\ \mathbf{x} \in \mathbb{R}^{n}, \mathbf{c} \in \mathbb{R}^{n}, A \in \mathbb{R}^{m \times n}, \mathbf{b} \in \mathbb{R}^{m} \end{array}$ 

- 1. "=" constraints
- 2.  $\mathbf{x} \ge \mathbf{0}$  nonnegativity constraints

4. max

Every LP problem can be transformed in eq. std. form

1. introduce slack variables (or surplus)

 $5x_1 + 10x_2 + x_3 = 60$  $4x_1 + 4x_2 + x_4 = 40$ 

Every LP problem can be transformed in eq. std. form

1. introduce slack variables (or surplus)

 $5x_1 + 10x_2 + x_3 = 60$  $4x_1 + 4x_2 + x_4 = 40$ 

2. if 
$$x_1 \stackrel{\geq}{_{<}} 0$$
 then  $\begin{array}{c} x_1 = x_1' - x_1'' \\ x_1' \ge 0 \\ x_1'' \ge 0 \end{array}$ 

Every LP problem can be transformed in eq. std. form

1. introduce slack variables (or surplus)

 $5x_1 + 10x_2 + x_3 = 60$  $4x_1 + 4x_2 + x_4 = 40$ 

2. if 
$$x_1 \gtrsim 0$$
 then  $\begin{array}{c} x_1 = x_1' - x_1'' \\ x_1' \geq 0 \\ x_1'' \geq 0 \end{array}$ 

**3**. (*b* ≥ 0)

Every LP problem can be transformed in eq. std. form

1. introduce slack variables (or surplus)

 $5x_1 + 10x_2 + x_3 = 60$  $4x_1 + 4x_2 + x_4 = 40$ 

2. if 
$$x_1 \gtrsim 0$$
 then  $\begin{array}{c} x_1 = x_1' - x_1' \\ x_1' \geq 0 \\ x_1'' \geq 0 \end{array}$ 

- 3. ( $b \ge 0$ )
- 4. min  $c^T x \equiv \max(-c^T x)$

Every LP problem can be transformed in eq. std. form

1. introduce slack variables (or surplus)

 $5x_1 + 10x_2 + x_3 = 60$  $4x_1 + 4x_2 + x_4 = 40$ 

2. if 
$$x_1 \stackrel{>}{_{<}} 0$$
 then  $\begin{array}{c} x_1 = x_1' - x_1'' \\ x_1' \ge 0 \\ x_1'' \ge 0 \end{array}$ 

- **3**. (*b* ≥ 0)
- 4. min  $c^T x \equiv \max(-c^T x)$

LP in  $n \times m$  converted into LP with at most (m + 2n) variables and m equations (n # original variables, m # constraints)

# Geometry of LP in Eq. Std. Form

$$\max\{\mathbf{c}^{\mathsf{T}}\mathbf{x} \mid A\mathbf{x} = \mathbf{b}, \mathbf{x} \ge \mathbf{0}\}$$

From linear algebra:

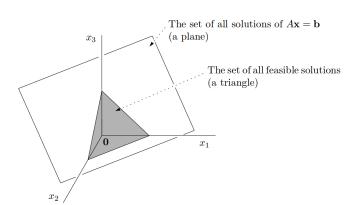
- the set of solutions of  $A\mathbf{x} = \mathbf{b}$  is an affine space (plane not passing through the origin).
- $x \geq 0$  nonegative orthant (octant in  $\mathbb{R}^3)$

# Geometry of LP in Eq. Std. Form

 $\max\{\mathbf{c}^{\mathsf{T}}\mathbf{x} \mid A\mathbf{x} = \mathbf{b}, \mathbf{x} > \mathbf{0}\}$ 

From linear algebra:

- the set of solutions of Ax = b is an affine space (plane not passing through the origin).
- $x \geq 0$  nonegative orthant (octant in  $\mathbb{R}^3)$



In  $\mathbb{R}^3$ :

•  $A\mathbf{x} = \mathbf{b}$  is a system of equations that we can solve by Gaussian elimination

- $A\mathbf{x} = \mathbf{b}$  is a system of equations that we can solve by Gaussian elimination
- Elementary row operations of  $\begin{bmatrix} A & | & \mathbf{b} \end{bmatrix}$  do not affect set of feasible solutions

- $A\mathbf{x} = \mathbf{b}$  is a system of equations that we can solve by Gaussian elimination
- Elementary row operations of  $\begin{bmatrix} A & b \end{bmatrix}$  do not affect set of feasible solutions
  - multiplying all entries in some row of  $[A \mid \mathbf{b}]$  by a nonzero real number  $\lambda$

- $A\mathbf{x} = \mathbf{b}$  is a system of equations that we can solve by Gaussian elimination
- Elementary row operations of  $\begin{bmatrix} A & b \end{bmatrix}$  do not affect set of feasible solutions
  - multiplying all entries in some row of  $\begin{bmatrix} A & b \end{bmatrix}$  by a nonzero real number  $\lambda$
  - replacing the *i*th row of  $\begin{bmatrix} A & b \end{bmatrix}$  by the sum of the *i*th row and *j*th row for some  $i \neq j$

- $A\mathbf{x} = \mathbf{b}$  is a system of equations that we can solve by Gaussian elimination
- Elementary row operations of  $\begin{bmatrix} A & b \end{bmatrix}$  do not affect set of feasible solutions
  - multiplying all entries in some row of  $[A \mid \mathbf{b}]$  by a nonzero real number  $\lambda$
  - replacing the *i*th row of  $\begin{bmatrix} A & b \end{bmatrix}$  by the sum of the *i*th row and *j*th row for some  $i \neq j$
- We assume  $n \ge m$  and

 $\operatorname{rank}([A \mid \mathbf{b}]) = \operatorname{rank}(A) = m$ 

, ie, rows of A are linearly independent otherwise, remove linear dependent rows

# Outline

### 1. Simplex Method Standard Form Basic Feasible Solutions Algorithm

ableaux and Dictionaries

## **Basic Feasible Solutions**

Basic feasible solutions are the vertices of the feasible region:



## **Basic Feasible Solutions**

Basic feasible solutions are the vertices of the feasible region:



More formally: Let  $B = \{1 \dots m\}$ ,  $N = \{m + 1 \dots n + m\}$  be subsets partitioning the columns of A:  $A_B$  be made of columns of A indexed by B:

## **Basic Feasible Solutions**

Basic feasible solutions are the vertices of the feasible region:



More formally:

Let  $B = \{1 \dots m\}$ ,  $N = \{m + 1 \dots n + m\}$  be subsets partitioning the columns of A:  $A_B$  be made of columns of A indexed by B:

### Definition

 $\mathbf{x} \in \mathbb{R}^n$  is a basic feasible solution of the linear program  $\max{\{\mathbf{c}^T \mathbf{x} \mid A\mathbf{x} = \mathbf{b}, \mathbf{x} \ge \mathbf{0}\}}$  for an index set *B* if:

- $x_j = 0 \ \forall j \notin B$
- the square matrix  $A_B$  is nonsingular, ie, all columns indexed by B are lin. indep.
- $\mathbf{x}_B = A_B^{-1} \mathbf{b}$  is nonnegative, ie,  $\mathbf{x}_B \ge 0$  (feasibility)

We call  $x_j$  for  $j \in B$  basic variables and remaining variables nonbasic variables.

### Theorem

A basic feasible solution is uniquely determined by the set B.

Proof:

$$Ax = A_B x_B + A_N x_N = b$$
  

$$x_B + A_B^{-1} A_N x_N = A_B^{-1} b$$
  

$$x_B = A_B^{-1} b$$
  

$$A_B \text{ is singular hence one solution}$$

Note: we call B a (feasible) basis

### Theorem

Let P be a (convex) polyhedron from LP in std. form. For a point  $v \in P$  the following are equivalent:

- (i) v is an extreme point (vertex) of P
- (ii) v is a basic feasible solution of LP

### Theorem

Let P be a (convex) polyhedron from LP in std. form. For a point  $v \in P$  the following are equivalent:

- (i) v is an extreme point (vertex) of P
- (ii) v is a basic feasible solution of LP

Proof: by recognizing that vertices of  ${\cal P}$  are linear independent and such are the columns in  ${\cal A}_{\cal B}$ 

### Theorem

Let P be a (convex) polyhedron from LP in std. form. For a point  $v \in P$  the following are equivalent:

- (i) v is an extreme point (vertex) of P
- (ii) v is a basic feasible solution of LP

Proof: by recognizing that vertices of  ${\cal P}$  are linear independent and such are the columns in  ${\cal A}_{\cal B}$ 

### Theorem

Let  $LP = \max{c^T \mathbf{x} \mid A\mathbf{x} = \mathbf{b}, \mathbf{x} \ge \mathbf{0}}$  be feasible and bounded, then the optimal solution is a basic feasible solution.

### Theorem

Let P be a (convex) polyhedron from LP in std. form. For a point  $v \in P$  the following are equivalent:

- (i) v is an extreme point (vertex) of P
- (ii) v is a basic feasible solution of LP

Proof: by recognizing that vertices of  ${\cal P}$  are linear independent and such are the columns in  ${\cal A}_{\cal B}$ 

### Theorem

Let  $LP = \max{c^T \mathbf{x} \mid A\mathbf{x} = \mathbf{b}, \mathbf{x} \ge \mathbf{0}}$  be feasible and bounded, then the optimal solution is a basic feasible solution.

Proof. consequence of previous theorem and fundamental theorem of linear programming

Idea for solution method: examine all basic solutions. There are finitely many:  $\binom{m+n}{m}$ . However, if n = m then  $\binom{2m}{m} \approx 4^m$ .

# Outline

### 1. Simplex Method

Standard Form Basic Feasible Solutions Algorithm Tableaux and Dictionaries

# Simplex Method

$$\max \quad z = \begin{bmatrix} 6 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
$$\begin{bmatrix} 5 & 10 & 1 & 0 \\ 4 & 4 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 60 \\ 40 \end{bmatrix}$$
$$x_1, x_2, x_3, x_4 \ge 0$$

Canonical eq. std. form: one decision variable is isolated in each constraint and does not appear in the other constraints nor in the obj. func. and *b* terms are positive

# Simplex Method

max 
$$z = \begin{bmatrix} 6 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
  
 $\begin{bmatrix} 5 & 10 & 1 & 0 \\ 4 & 4 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 60 \\ 40 \end{bmatrix}$   
 $x_1, x_2, x_3, x_4 \ge 0$ 

Canonical eq. std. form: one decision variable is isolated in each constraint and does not appear in the other constraints nor in the obj. func. and *b* terms are positive

It gives immediately a basic feasible solution:

 $x_1 = 0, x_2 = 0, x_3 = 60, x_4 = 40$ 

Is it optimal?

# Simplex Method

max 
$$z = \begin{bmatrix} 6 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
  
 $\begin{bmatrix} 5 & 10 & 1 & 0 \\ 4 & 4 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 60 \\ 40 \end{bmatrix}$   
 $x_1, x_2, x_3, x_4 \ge 0$ 

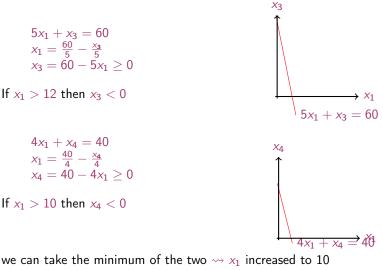
Canonical eq. std. form: one decision variable is isolated in each constraint and does not appear in the other constraints nor in the obj. func. and *b* terms are positive

It gives immediately a basic feasible solution:

 $x_1 = 0, x_2 = 0, x_3 = 60, x_4 = 40$ 

Is it optimal? Look at signs in  $z \rightsquigarrow$  if positive then an increase would improve.

Let's try to increase a promising variable, ie,  $x_{\rm l},$  one with positive coefficient in z



 $x_4$  exits the basis and  $x_1$  enters

# Simplex Tableau

First simplex tableau:



# Simplex Tableau

First simplex tableau:

we want to reach this new tableau

# Simplex Tableau

First simplex tableau:

	$x_1$	<i>x</i> <sub>2</sub>	<i>x</i> 3	<i>x</i> <sub>4</sub>	- <i>z</i> 0 0	Ь
<i>X</i> 3	5	10	1	0	0	60
<i>x</i> 4	4	4	0	1	0	40
	6	8	0	0	1	0

we want to reach this new tableau

#### Pivot operation:

1. Choose pivot:

column: one s with positive coefficient in obj. func. row: ratio between coefficient b and pivot column: choose the one with smallest ratio:

$$heta = \min_i \left\{ rac{b_i}{a_{is}} : a_{is} > 0 
ight\}, \qquad egin{array}{c} heta & ext{increase value} \ heta & ext{of entering var.} \end{array}$$

2. elementary row operations to update the tableau

- $x_4$  leaves the basis,  $x_1$  enters the basis
  - Divide pivot row by pivot
  - Send to zero the coefficient in the pivot column of the first row
  - Send to zero the coefficient of the pivot column in the third (cost) row

- $x_4$  leaves the basis,  $x_1$  enters the basis
  - Divide pivot row by pivot
  - Send to zero the coefficient in the pivot column of the first row
  - Send to zero the coefficient of the pivot column in the third (cost) row

 												ъI
I'=I-5II'   II'=II/4	 	0 1	 	5 1	 	1 0	 	-5/4 1/4	 	0 0	 	10   10
III'=III-6II'												

- $x_4$  leaves the basis,  $x_1$  enters the basis
  - Divide pivot row by pivot
  - · Send to zero the coefficient in the pivot column of the first row
  - · Send to zero the coefficient of the pivot column in the third (cost) row

From the last row we read:  $2x_2 - 3/2x_4 - z = -60$ , that is:  $z = 60 + 2x_2 - 3/2x_4$ . Since  $x_2$  and  $x_4$  are nonbasic we have z = 60 and  $x_1 = 10, x_2 = 0, x_3 = 10, x_4 = 0$ .

• Done?

- $x_4$  leaves the basis,  $x_1$  enters the basis
  - Divide pivot row by pivot
  - · Send to zero the coefficient in the pivot column of the first row
  - Send to zero the coefficient of the pivot column in the third (cost) row

From the last row we read:  $2x_2 - 3/2x_4 - z = -60$ , that is:  $z = 60 + 2x_2 - 3/2x_4$ . Since  $x_2$  and  $x_4$  are nonbasic we have z = 60 and  $x_1 = 10, x_2 = 0, x_3 = 10, x_4 = 0$ .

• Done? No! Let x<sub>2</sub> enter the basis

- $x_4$  leaves the basis,  $x_1$  enters the basis
  - Divide pivot row by pivot
  - · Send to zero the coefficient in the pivot column of the first row
  - Send to zero the coefficient of the pivot column in the third (cost) row

From the last row we read:  $2x_2 - 3/2x_4 - z = -60$ , that is:  $z = 60 + 2x_2 - 3/2x_4$ . Since  $x_2$  and  $x_4$  are nonbasic we have z = 60 and  $x_1 = 10, x_2 = 0, x_3 = 10, x_4 = 0$ .

• Done? No! Let x<sub>2</sub> enter the basis

### Definition (Reduced costs)

We call reduced costs the coefficients in the objective function of the nonbasic variables,  $\bar{c}_N$ 

### Definition (Reduced costs)

We call reduced costs the coefficients in the objective function of the nonbasic variables,  $\bar{c}_N$ 

#### Proposition (Optimality Condition)

The basic feasible solution is optimal when the reduced costs in the corresponding simplex tableau are nonpositive, ie, such that:

#### $\bar{c}_N \leq 0$

### Definition (Reduced costs)

We call reduced costs the coefficients in the objective function of the nonbasic variables,  $\bar{c}_N$ 

### Proposition (Optimality Condition)

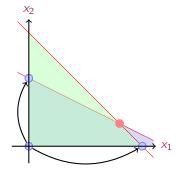
The basic feasible solution is optimal when the reduced costs in the corresponding simplex tableau are nonpositive, ie, such that:

#### $\bar{c}_N \leq 0$

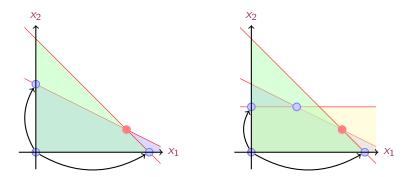
Proof: Let  $z_0$  be the obj value when  $\bar{c}_N \leq 0$ . For any other feasible solution  $\tilde{\mathbf{x}}$  we have:

$$\mathbf{\tilde{x}}_N \ge 0$$
 and  $\mathbf{c}^T \mathbf{\tilde{x}} = z_0 + \mathbf{\bar{c}}_N^T \mathbf{\tilde{x}}_N \le z_0$ 

# **Graphical Representation**



# **Graphical Representation**



# Outline

#### 1. Simplex Method

Standard Form Basic Feasible Solutions Algorithm Tableaux and Dictionaries

$$\max \sum_{\substack{j=1 \\ n \\ j=1}}^{n} c_j x_j$$
$$\sum_{\substack{j=1 \\ x_j \geq 0, j=1,\ldots,n}}^{n} a_{ij} x_j \leq b_i, i = 1,\ldots, m$$

$$\max \sum_{\substack{j=1 \\ j=1}^{n} c_{j}x_{j}}^{n} c_{j}x_{j} \leq b_{i}, \ i = 1, \dots, m \\ x_{j} \geq 0, \ j = 1, \dots, n \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_{j} \geq 0, \ x_{j} \geq 0, \\ x_{j} \geq 0, \ x_$$

$$\max \sum_{\substack{j=1 \\ n \\ j=1}}^{n} c_j x_j$$
$$\sum_{\substack{j=1 \\ x_j \geq 0, j=1,\ldots,n}}^{n} a_{ij} x_j \leq b_i, i = 1,\ldots, m$$

$$x_{n+i} = b_i - \sum_{j=1}^n a_{ij} x_j, \quad i = 1, \dots, m$$
$$z = \sum_{j=1}^n c_j x_j$$

#### Tableau

Dictionary

$$\begin{bmatrix} I & \bar{A}_{N} & 0 & \bar{b} \\ 0 & \bar{c}_{N} & 1 & -\bar{d} \end{bmatrix}$$

$$\begin{aligned} x_r &= \bar{b}_r - \sum_{s \notin B} \bar{a}_{rs} x_s, \quad r \in B \\ z &= \bar{d} + \sum_{s \notin B} \bar{c}_s x_s \end{aligned}$$

$$\max \sum_{\substack{j=1 \\ n \\ j=1}}^{n} c_j x_j$$
$$\sum_{\substack{j=1 \\ x_j \geq 0, j=1,\ldots,n}}^{n} a_{ij} x_j \leq b_i, i = 1,\ldots, m$$

$$x_{n+i} = b_i - \sum_{j=1}^n a_{ij} x_j, \quad i = 1, \dots, m$$
$$z = \sum_{j=1}^n c_j x_j$$

#### Tableau

Dictionary

$$\begin{bmatrix} I & \bar{A}_N & 0 & \bar{b} \\ 0 & \bar{c}_N & 1 & -\bar{d} \end{bmatrix}$$

 $\begin{aligned} x_r &= \bar{b}_r - \sum_{s \notin B} \bar{a}_{rs} x_s, \quad r \in B \\ z &= \bar{d} + \sum_{s \notin B} \bar{c}_s x_s \end{aligned}$ 

pivot operations in dictionary form: choose col s with r.c. > 0 choose row with min{ $-\bar{b}_i/\bar{a}_{is} \mid a_{is} < 0, i = 1, \ldots, m$ } update: express entering variable and substitute in other rows

### Example

$$x_3 = 60 - 5x_1 - 10x_2$$
  

$$x_4 = 40 - 4x_1 - 4x_2$$
  

$$z = + 6x_1 + 8x_2$$

### Example

After 2 iterations:

$$x_3 = 60 - 5x_1 - 10x_2$$
  

$$x_4 = 40 - 4x_1 - 4x_2$$
  

$$z = + 6x_1 + 8x_2$$

# Summary

#### 1. Simplex Method

Standard Form Basic Feasible Solutions Algorithm Tableaux and Dictionaries