a core model for choreographic programming

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facs'16, besançon, france october 21st, 2016

outline

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the zoo of communication

communication & computation

practical consequences

models of communicating systems

process calculi

 π -calculus and its variants

- low-level modeling of communication
- too technical for many purposes
- many interesting fragments are undecidable

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chore ographies

- global view of the system
- directed communication (from alice to bob)

- deadlock-free by design
- compilable to process calculi

choreographies and computation

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 $\sim \rightarrow$

trivially turing-complete (arbitrary computation at each process)

choreographies and computation

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 typically geared towards applications (many complex primitives)

choreographies and computation

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focus communication

- reduce local computation to a minimum
- reduce system primitives to a minimum

how far can we go?

our contribution

i/o-based notion of function implementation

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- computation by message-passing
- reminiscent of memory models (e.g. urm)

our contribution

i/o-based notion of function implementation

- computation by message-passing
- reminiscent of memory models (e.g. urm)

focus of this talk:

- minimal choreographies
- their turing completeness

outline

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the zoo oj communication

 $\begin{array}{c} communication \\ {\it {\it E}} \ computation \end{array}$

practical consequences

typical primitives in choreographies

- termination
- message passing
- label selection
- conditionals
- recursion

. . .

- process creation
- channel creation
- channel passing
- role assignment

typical primitives in choreographies

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minimal choreographies

$$M ::= \mathbf{0} \mid \eta; M \mid \text{if } (p.* = q.*) \text{ then } M_1 \text{ else } M_2$$
$$\mid \text{def } X = M_2 \text{ in } M_1 \mid X$$

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$$\eta ::= \mathsf{p}.e \to \mathsf{q} \mid \mathsf{p} \to \mathsf{q}[l]$$

 $l ::= \mathrm{L} \mid \mathrm{R}$

$$\mathbf{e} ::= \varepsilon \mid \mathbf{s} \mid \mathbf{s} \cdot \mathbf{*}$$

minimal choreographies

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urm machine

classical model of computation

- similar to physical memory
- memory cells store natural numbers
- memory operations: zero, successor, copy
- jump-on-equal

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urm machine

classical model of computation

- similar to physical memory
- memory cells store natural numbers ~→ processes
- memory operations: zero, successor, copy
- jump-on-equal \rightsquigarrow conditional / loop

 $\begin{array}{c} minimal \\ choreographies \end{array}$

but...!

$$M ::= \mathbf{0} \mid \eta; M \mid \text{if } (p.* = q.*) \text{ then } M_1 \text{ else } M_2$$
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$$\eta ::= p.e \rightarrow q \mid p \rightarrow q[l]$$
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very different computation model

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- no centralized control
- no self-change

minimal choreographies

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$on \ selections$

- not needed for computational completeness
- useful for projectability (e.g. to π -calculus)
- known algorithms for inferring selections

implementation of functions

state a *state* of an minimal choreography is a mapping from the set of process names to the set of values

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implementation of functions

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implementation choreography M implements $f : \mathbb{N}^n \to \mathbb{N}$ with inputs p_1, \ldots, p_n and output q if: for every σ such that $\sigma(p_i) = \lceil x_i \rceil$,

- if $f(\tilde{x})$ is defined, then $M, \sigma \to^* \mathbf{0}, \sigma'$ and $\sigma'(q) = \lceil f(\tilde{x}) \rceil$
- if $f(\tilde{x})$ is not defined, then $M, \sigma \not\rightarrow^* \mathbf{0}$ (diverges)

addition from p, q to r using t
$$\begin{split} \operatorname{def} X &= \\ & \operatorname{if} \left(\mathrm{r}.* = \mathrm{q}.* \right) \operatorname{then} \\ & \mathrm{p}.* \to \mathrm{r}; \ \mathbf{0} \\ & \operatorname{else} \\ & & \operatorname{p}.* \to \mathrm{t}; \ \mathrm{t}.(\mathrm{s} \cdot *) \to \mathrm{p}; \\ & & \operatorname{r}.* \to \mathrm{t}; \ \mathrm{t}.(\mathrm{s} \cdot *) \to \mathrm{r}; \ X \\ & \operatorname{in} \mathrm{t}.\varepsilon \to \mathrm{r}; \ X \end{split}$$

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 \rightsquigarrow does not compile!

- projection of p does not know whether to send a message to r or t
- projection of t does not know whether to wait for a message or terminate

 $\begin{array}{c} addition \\ from \ \mathsf{p}, \ \mathsf{q} \ to \ \mathsf{r} \\ using \ \mathsf{t} \end{array} \quad def \ X = \\ \begin{array}{c} from \ \mathsf{p}, \ \mathsf{q} \ to \ \mathsf{r} \\ from \ \mathsf{r} \end{array}$

$$\begin{array}{l} \text{der } \mathcal{X} = \\ & \text{if } (\mathbf{r}.* = \mathbf{q}.*) \, \text{then } \mathbf{r} \rightarrow \mathbf{p}[\mathrm{L}]; \, \mathbf{r} \rightarrow \mathbf{q}[\mathrm{L}]; \, \mathbf{r} \rightarrow \mathbf{t}[\mathrm{L}]; \\ & \text{p}.* \rightarrow \mathbf{r}; \, \mathbf{0} \\ & \text{else } \mathbf{r} \rightarrow \mathbf{p}[\mathrm{R}]; \, \mathbf{r} \rightarrow \mathbf{q}[\mathrm{R}]; \, \mathbf{r} \rightarrow \mathbf{t}[\mathrm{R}]; \\ & \text{p}.* \rightarrow \mathbf{t}; \, \mathbf{t}.(\mathbf{s} \cdot *) \rightarrow \mathbf{p}; \\ & \text{r}.* \rightarrow \mathbf{t}; \, \mathbf{t}.(\mathbf{s} \cdot *) \rightarrow \mathbf{r}; \, X \\ & \text{in } \mathbf{t}.\varepsilon \rightarrow \mathbf{r}; \, X \end{array}$$

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addition from p, q to r using t
$$\begin{split} & \mathsf{def} \ X = \\ & \mathsf{if} \ (\mathsf{r}.* = \mathsf{q}.*) \, \mathsf{then} \, \mathsf{r} \to \mathsf{p}[\mathtt{L}]; \ \mathsf{r} \to \mathsf{q}[\mathtt{L}]; \ \mathsf{r} \to \mathsf{t}[\mathtt{L}]; \\ & \mathsf{p}.* \to \mathsf{r}; \ \mathbf{0} \\ & \mathsf{else} \, \mathsf{r} \to \mathsf{p}[\mathtt{R}]; \ \mathsf{r} \to \mathsf{q}[\mathtt{R}]; \ \mathsf{r} \to \mathsf{t}[\mathtt{R}]; \\ & \mathsf{p}.* \to \mathsf{t}; \ \mathsf{t}.(\mathsf{s} \cdot *) \to \mathsf{p}; \\ & \mathsf{r}.* \to \mathsf{t}; \ \mathsf{t}.(\mathsf{s} \cdot *) \to \mathsf{r}; \ X \\ & \mathsf{in} \, \mathsf{t}.\varepsilon \to \mathsf{r}; \ X \end{split}$$

 \rightsquigarrow compiles!

projections of p and t wait for notification from r

projection of q also needs to be notified

partial recursive functions i/vi

$$S: \mathbb{N} \to \mathbb{N}$$
 such that $S(x) = x + 1$ for all x

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partial recursive functions i/vi

successor

$$S:\mathbb{N} \to \mathbb{N}$$
 such that $S(x) = x + 1$ for all x

implementation

$$\llbracket S \rrbracket^{\mathsf{p} \mapsto \mathsf{q}} = \mathsf{p}.(\mathsf{s} \cdot *) \to \mathsf{q}$$

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partial recursive functions i/vi

successor

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$$S:\mathbb{N} o\mathbb{N}$$
 such that $S(x)=x+1$ for all x

$$\llbracket S \rrbracket^{\mathsf{p} \mapsto \mathsf{q}} = \mathsf{p}.(\mathsf{s} \cdot \ast) \to \mathsf{q}$$

soundness

$$\mathsf{p}.(\mathsf{s}\cdot\ast)\to\mathsf{q},\{\mathsf{p}\mapsto\ulcorner x\urcorner\}\longrightarrow\mathbf{0},\left\{\begin{matrix}\mathsf{p}\mapsto\ulcorner x\urcorner\\\mathsf{q}\mapsto\ulcorner x+1\urcorner\end{matrix}\right\}$$

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partial recursive functions ii/vi $Z: \mathbb{N} \to \mathbb{N}$ such that Z(x) = 0 for all x zeroimplementation $\llbracket Z \rrbracket^{\mathsf{p} \mapsto \mathsf{q}} = \mathsf{p}.\varepsilon \to \mathsf{q}$ soundness $\mathsf{p}.\varepsilon \to \mathsf{q}, \{\mathsf{p} \mapsto \ulcorner x \urcorner\} \longrightarrow \mathbf{0}, \left\{ \begin{matrix} \mathsf{p} \mapsto \ulcorner x \urcorner \\ \mathsf{q} \mapsto \ulcorner 0 \urcorner \end{matrix} \right\}$

partial recursive functions iii/vi

projections

implementation

$$P_m^n:\mathbb{N}\to\mathbb{N}$$
 such that $P_m^n(x_1,\ldots,x_n)=x_m$ for all \tilde{x}

$$\llbracket P_m^n \rrbracket^{p_1,\ldots,p_n \mapsto q} = p_m . * \to q$$

soundness

$$\mathsf{p}_{\mathsf{m}}.* \to \mathsf{q}, \{\mathsf{p}_{\mathsf{i}} \mapsto \ulcorner x_{\mathsf{i}} \urcorner\} \longrightarrow \mathbf{0}, \begin{cases} \mathsf{p}_{\mathsf{i}} \mapsto \ulcorner x_{\mathsf{i}} \urcorner\\ \mathsf{q} \mapsto \ulcorner x_{\mathsf{m}} \urcorner \end{cases}$$

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inductive cases (omitted)

three recursive constructions (see paper)

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- composition
- recursion
- minimization

→ composition executes in parallel

minimality

minimal choreographies

 $M ::= \mathbf{0} | \eta; M | \text{ if } (p.* = q.*) \text{ then } M_1 \text{ else } M_2$ $| \text{ def } X = M_2 \text{ in } M_1 | X$ $\eta ::= p.e \rightarrow q | p \rightarrow q[I]$ I ::= L | R $e ::= \varepsilon | * | s \cdot *$

- no exit points ~> nothing terminates
- no communication ~→ no output
- less expressions ~→ cannot compute base cases
- no conditions ~> termination is decidable
- no recursion ~> everything terminates

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- only zero-testing → termination is decidable (skipping proof...)
- only (arbitrary) constant-testing → termination is decidable

minimality

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selections can be encoded as communications (but...)

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outline

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the zoo oj communication

 $\begin{array}{c} communication\\ {\mathfrak S} \ computation \end{array}$

 $practical \\ consequences$

sound encoding of partial recursive functions as minimal choreographies

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- sound encoding of partial recursive functions as minimal choreographies
- by embedding into other choreography models ~→ sound encoding of partial recursive functions in that model

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- by adding necessary selections (deterministically) ~→ sound encoding of partial recursive functions as minimal processes

- sound encoding of partial recursive functions as minimal choreographies
- by embedding into other choreography models → sound encoding of partial recursive functions in that model
- by adding necessary selections (deterministically) ~→ sound encoding of partial recursive functions as minimal processes
- by adding necessary selections and embedding into other choreography models → sound encoding of partial recursive functions in a process model (in particular, π-calculus)

conclusions

- turing completeness of minimal choreographies
- minimal set of primitives
- identifies a deadlock-free, turing-complete fragment of π -calculus
- core language for studying fundamental properties of choreographies

thank you!