choreography extraction

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the goal

extract a choreography from an implementation of a distributed system (if possible)

unsatisfactory state-of-the-art

- too complex (encode, apply algorithm, reencode, optimize, reencode, recompute, get unreadable result)
- too complex (super-factorial)
- kind of ad-hoc (non-standard languages)

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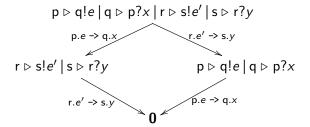
our privileged position

- nice languages for choreographies and processes
- intuitive description of what extraction should be (some kind of adjoint to epp)
- cool idea (symbolic execution)

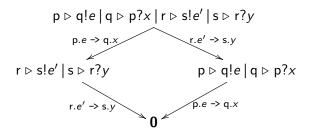
extraction by example (i/iii)

 $p \triangleright q!e \mid q \triangleright p?x \mid r \triangleright s!e' \mid s \triangleright r?y$

extraction by example (i/iii)



extraction by example (i/iii)

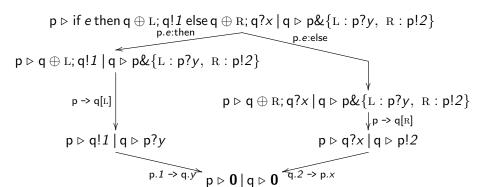


extracted choreography: p.e \rightarrow q.x; r.e' \rightarrow s.y or r.e' \rightarrow s.y; p.e \rightarrow q.x

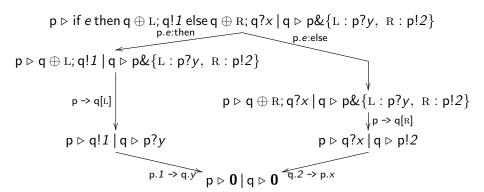
extraction by example (ii/iii)

 $\mathsf{p} \mathrel{\vartriangleright} \mathsf{if} \; \mathsf{e} \; \mathsf{then} \; \mathsf{q} \oplus \mathsf{L}; \; \mathsf{q} ! \; \mathsf{1} \; \mathsf{else} \; \mathsf{q} \oplus \mathsf{R}; \; \mathsf{q} ? x \; \big| \; \mathsf{q} \mathrel{\vartriangleright} \mathsf{p} \& \{ \mathsf{L} : \mathsf{p} ? y, \; \; \mathsf{R} : \mathsf{p} ! \; \mathsf{2} \}$

extraction by example (ii/iii)



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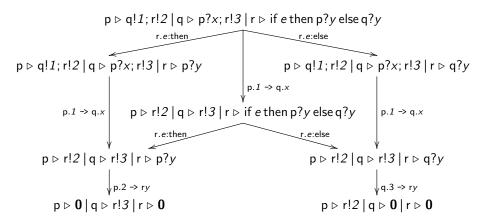


extracted choreography: if p.e then $(p \rightarrow q[L]; p.1 \rightarrow q.y)$ else $(p \rightarrow q[R]; q.2 \rightarrow p.x)$

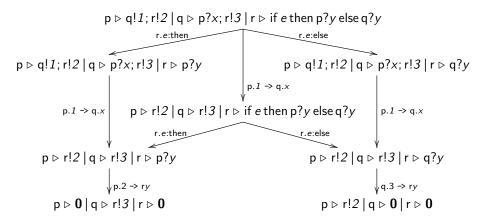
extraction by example (iii/iii)

 $p \triangleright q!1$; $r!2 \mid q \triangleright p?x$; $r!3 \mid r \triangleright if e then <math>p?y$ else q?y

extraction by example (iii/iii)



extraction by example (iii/iii)



all paths in the graph end in a deadlocked state, so the network cannot be extracted to a choreography

properties (finite case)

- termination
- soundness (the extracted choreography is bisimilar to the network)
- completeness (deadlock-free networks are extractable)
- efficient-ish (polynomial in the size of the network, graph size linear in the size of the extracted choreography)

dealing with recursion

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the good ones

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the not-so-good ones

- incompleteness (no can do: deadlock-freedom is undecidable)
- horrible complexity (graph size exponential in the size of the extracted choreography)

(still better than previous state-of-the-art)

imple mentation

creative solutions

- list of bad nodes
- choice paths
- some global variables
- parallelization
- extraction strategies
- livelocks
- three-valued logic for clever backtracking

testing

methodology

- examples from state-of-the-art
- reverse epp
- network fuzzer
- network scrambler

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bottom line

→ it kind of actually works :-)

status and future work

- journal article in progress, expected submission in the winter
- generalize with process spawning

thank you!